

Pohyb projektilu

> eqx := m*diff(vx(t),t) + b*vx(t) = 0;

$$eqx \rightarrow m \left(\frac{d}{dt} vx(t) \right) + b vx(t) = 0 \quad (1)$$

> eqy := m*diff(vy(t),t) + b*vy(t) + m*g = 0;

$$eqy \rightarrow m \left(\frac{d}{dt} vy(t) \right) + b vy(t) + m g = 0 \quad (2)$$

> sol := dsolve({eqx, eqy, vx(0)=v0x, vy(0)=v0y},
{vx(t), vy(t)});

$$sol \rightarrow \left\{ vx(t) = v0x e^{-\frac{b t}{m}}, vy(t) = \frac{L m g C e^{-\frac{b t}{m}} (b v0y C m g)}{b} \right\} \quad (3)$$

> simplify(sol);

$$\left\{ vx(t) = v0x e^{-\frac{b t}{m}}, vy(t) = \frac{e^{-\frac{b t}{m}} b v0y C e^{-\frac{b t}{m}} g m L m g}{b} \right\} \quad (4)$$

> subs(sol, {eqx, eqy});

$$\left\{ m \left(\frac{v}{vt} \left(\frac{L m g C e^{-\frac{b t}{m}} (b v0y C m g)}{b} \right) \right) C e^{-\frac{b t}{m}} (b v0y C m g) = 0, m \left(\frac{v}{vt} \left(v0x e^{-\frac{b t}{m}} \right) \right) C b v0x e^{-\frac{b t}{m}} = 0 \right\} \quad (5)$$

> simplify(%);

$$\{0 = 0\} \quad (6)$$

> assign(sol);

> vx(t);

$$v0x e^{-\frac{b t}{m}} \quad (7)$$

> vy(t);

$$\frac{L m g C e^{-\frac{b t}{m}} (b v0y C m g)}{b} \quad (8)$$

> limit(vx(t), t=0);

$$v0x \quad (9)$$

> limit(vy(t), t=0);

$$v0y \quad (10)$$

> limit(vx(t), b=0);

$$v0x \quad (11)$$

> limit(vy(t), b=0);

$$L t g C v0y \quad (12)$$

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> series(vx(t), t, 3);
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$$v_{0x} L \frac{v_{0x} b}{m} t C \frac{1}{2} \frac{v_{0x} b^2}{m^2} t^2 C O(t^3) \quad (13)$$

```
> series(vy(t), t, 3);
```

$$v_{0y} L \frac{b v_{0y} C m g}{m} t C \frac{1}{2} \frac{b (b v_{0y} C m g)}{m^2} t^2 C O(t^3) \quad (14)$$

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> limit(vy(t), t=infinity);
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$$\lim_{t \rightarrow \infty} \frac{L m g C e^{\frac{b t}{m}} (b v_{0y} C m g)}{b} \quad (15)$$

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> assume(m>0, b>0);
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> limit(vx(t), t=infinity);
```

$$\lim_{t \rightarrow \infty} v_{0x} e^{\frac{b t}{m}} \quad (16)$$

```
> limit(vy(t), t=infinity);
```

$$\lim_{t \rightarrow \infty} \frac{L m g C e^{\frac{b t}{m}} (b v_{0y} C m g)}{b} \quad (17)$$

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> b := 'b': m := 'm':
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> VX := unapply(vx(t), b, t);
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$$VX_d(b, t) = v_{0x} e^{\frac{b t}{m}} \quad (18)$$

```
> VY := unapply(vy(t), b, t);
```

$$VY_d(b, t) = \frac{L m g C e^{\frac{b t}{m}} (b v_{0y} C m g)}{b} \quad (19)$$

```
> X := unapply(int(vx(t), t=0..s), b, s);
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$$X_d(b, s) = L \frac{m v_{0x} \left(e^{\frac{b s}{m}} - 1 \right)}{b} \quad (20)$$

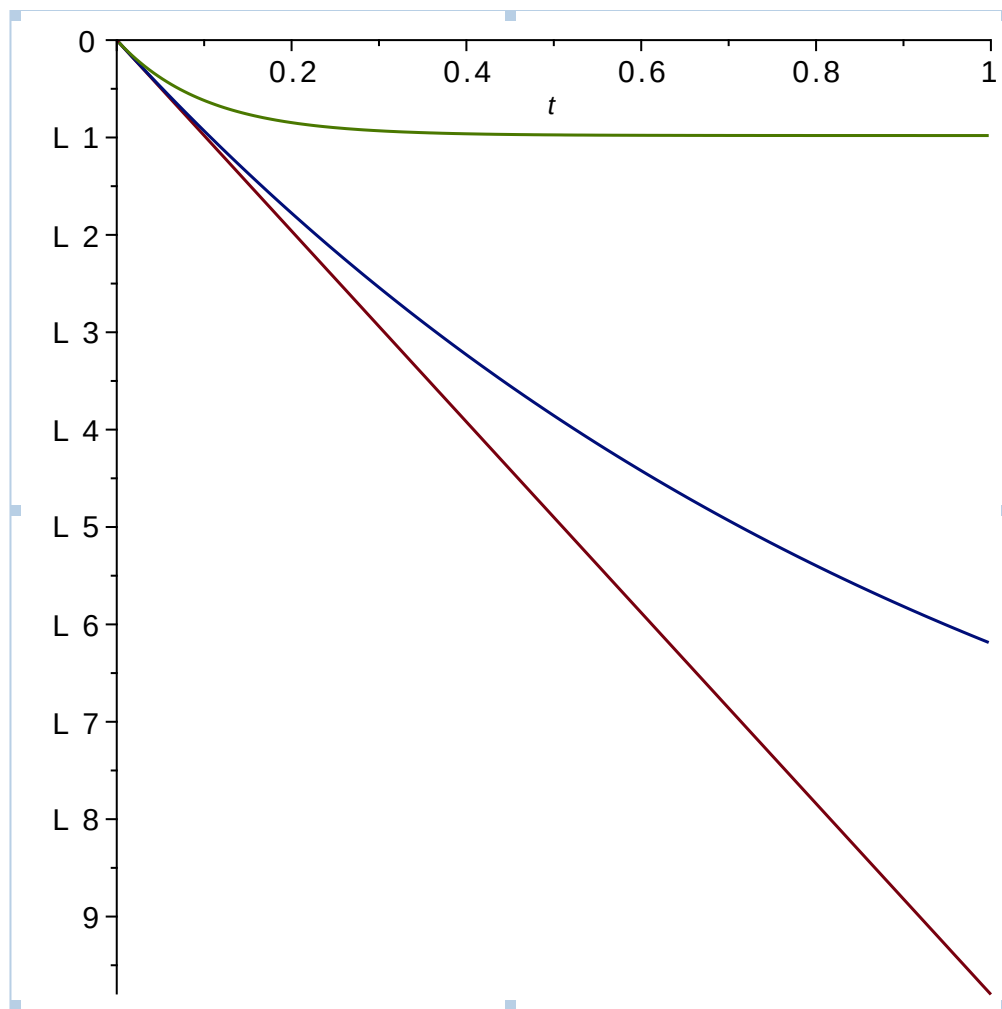
```
> Y := unapply(int(vy(t), t=0..s), b, s);
```

$$Y_d(b, s) = L \frac{m \left(e^{\frac{b s}{m}} - 1 \right) v_{0y} C e^{\frac{b s}{m}} g m C g b L b v_{0y} L m g}{b^2} \quad (21)$$

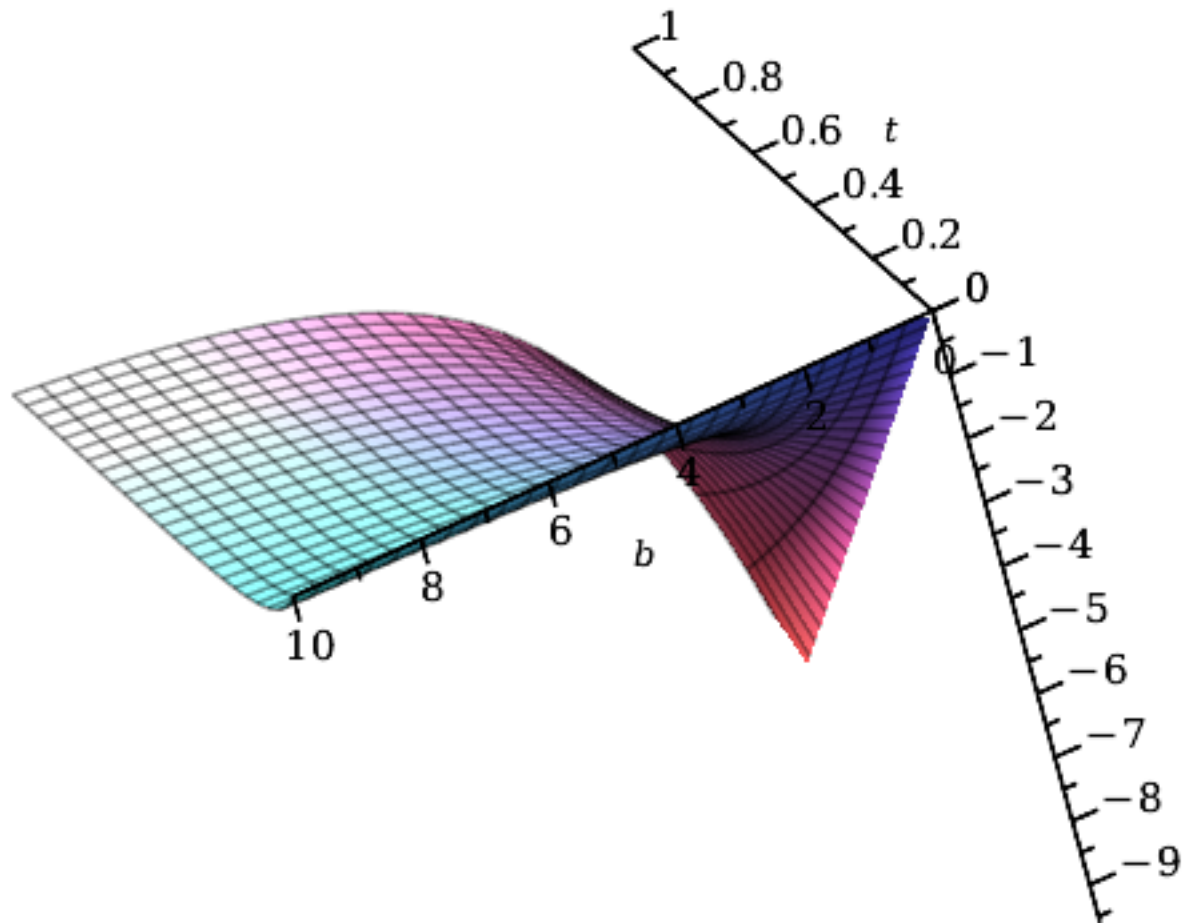
```
> m:=1: g:=9.8: v0x:=0: v0y:=0;
```

$$v_{0y} d = 0 \quad (22)$$

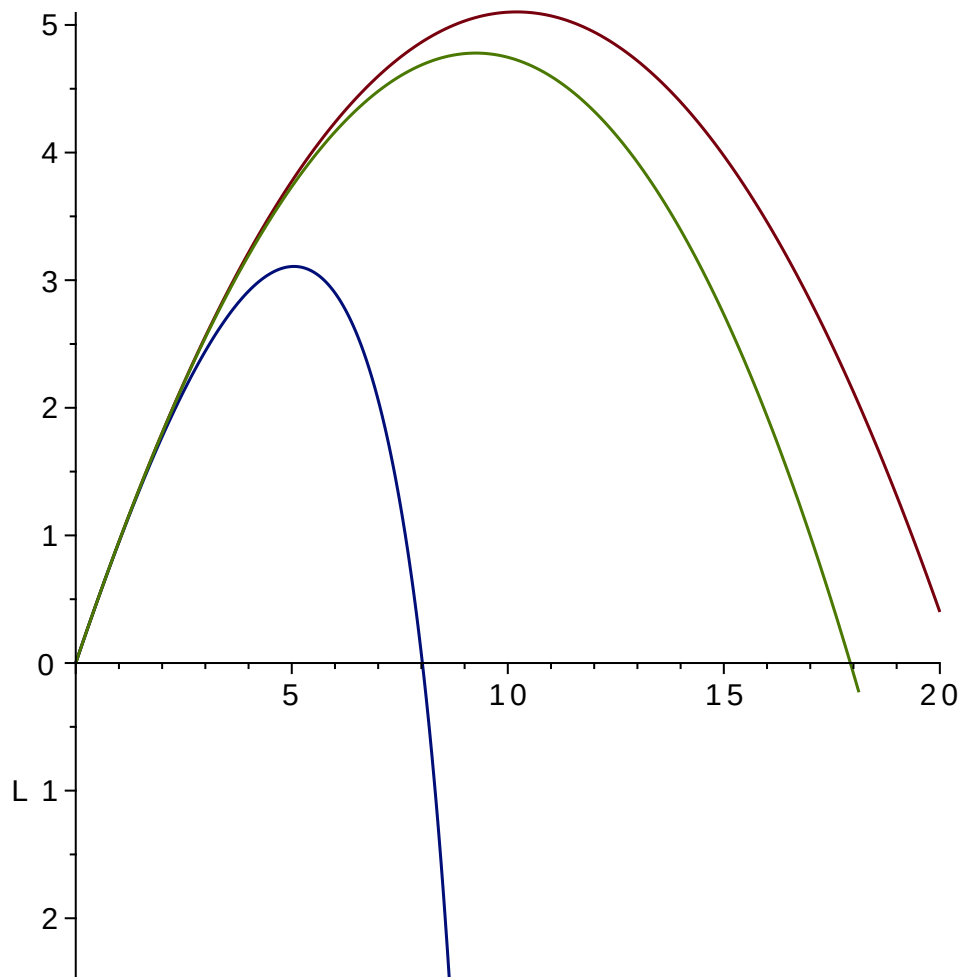
```
> plot({limit(VY(b,t), b=0), VY(1,t), VY(10,t)}, t=0..1);
```



```
> plot3d(VY(b,t), t=0..1, b=0..10,orientation=[-60,75],
axes=NORMAL);
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```
> v0x:=10: v0y:=10:
> plot({[limit(X(b,t),b=0), limit(Y(b,t),b=0),t=0..2], [X(.1,t), Y(.1,
t), t=0..2], [X(1,t), Y(1,t), t=0..2]});
```



```
> Pgrav := (b,t) -> m*g*abs(VY(b,t));
      Pgravd (b,t) m$g$|VY(b,t)| (23)
```

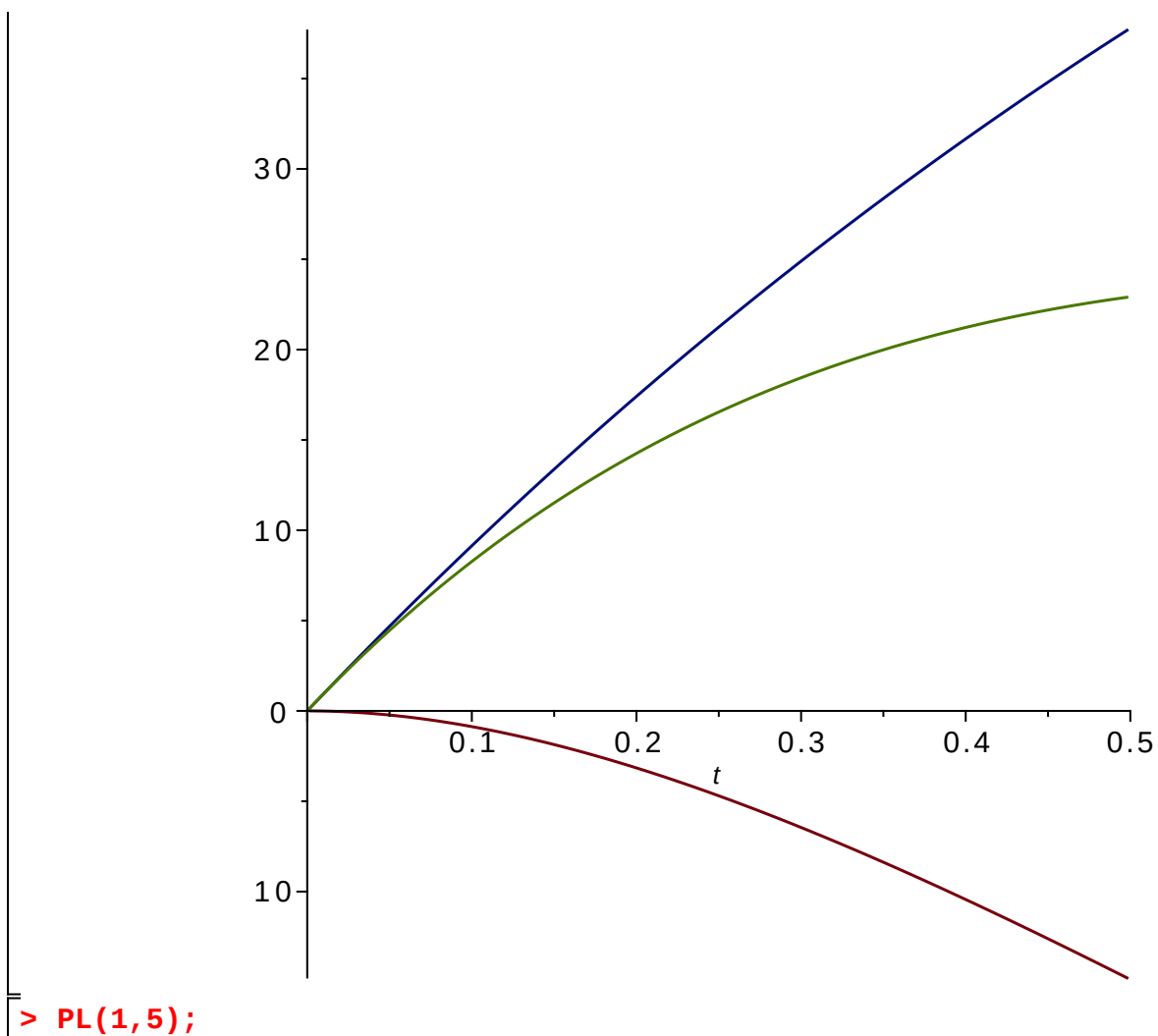
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> Pdrag := (b,t) -> -b*VY(b,t)^2;
      Pdragd (b,t) L b$VY(b,t)^2 (24)
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> Pnet := (b,t) -> Pgrav(b,t) + Pdrag(b,t);
      Pnetd (b,t) Pgrav(b,t) + Pdrag(b,t) (25)
```

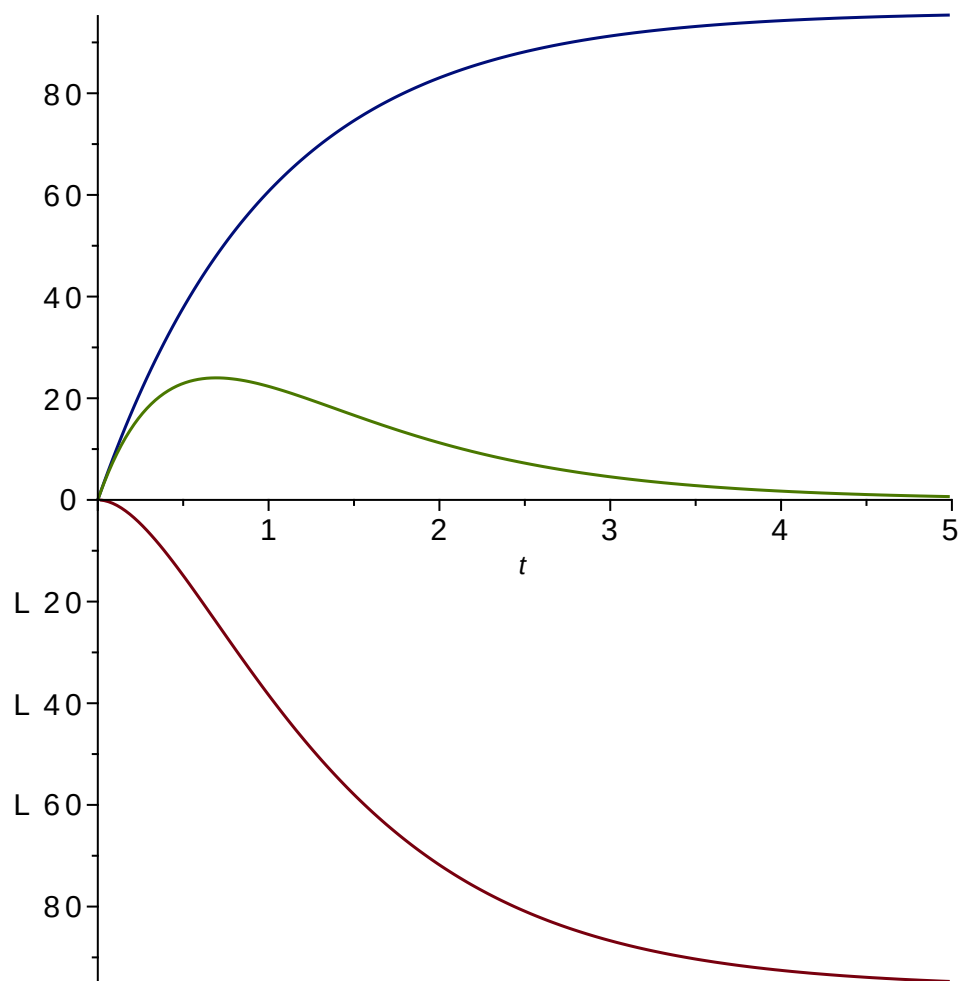
```
> PL := (b,T) -> plot({Pgrav(b,t), Pdrag(b,t), Pnet(b,t)}, t=0..T);
      PLd (b,T) plot({Pdrag(b,t), Pgrav(b,t), Pnet(b,t)}, t = 0..T) (26)
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```
> m :=1: g := 9.8: v0y := 0:
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> PL(1,0.5);
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> PL(1,5);



>