

# Development and Validation of a New Predictive Simulation Code using Multiscale Material Models

Alice Koniges,<sup>1</sup> Aaron Fisher,<sup>1</sup> Nathan Masters,<sup>1</sup> Parag Dixit,<sup>2</sup> Robert Anderson,<sup>1</sup> David Benson,<sup>2</sup> Brian Gunney,<sup>1</sup> Tom Kaiser,<sup>1</sup> David Eder,<sup>1</sup> Dan Kalantar,<sup>1</sup> William Brown,<sup>1</sup> Marc Meyers,<sup>2</sup> H. Jarmakani,<sup>2</sup> Betsy Foote<sup>1</sup>



<sup>1</sup> Lawrence Livermore National Laboratory,

<sup>2</sup> University of California, San Diego



Numerical methods for multi-material flows, Prague, CZ, Sept. 10 - 14, 2007



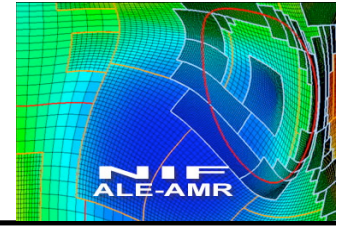
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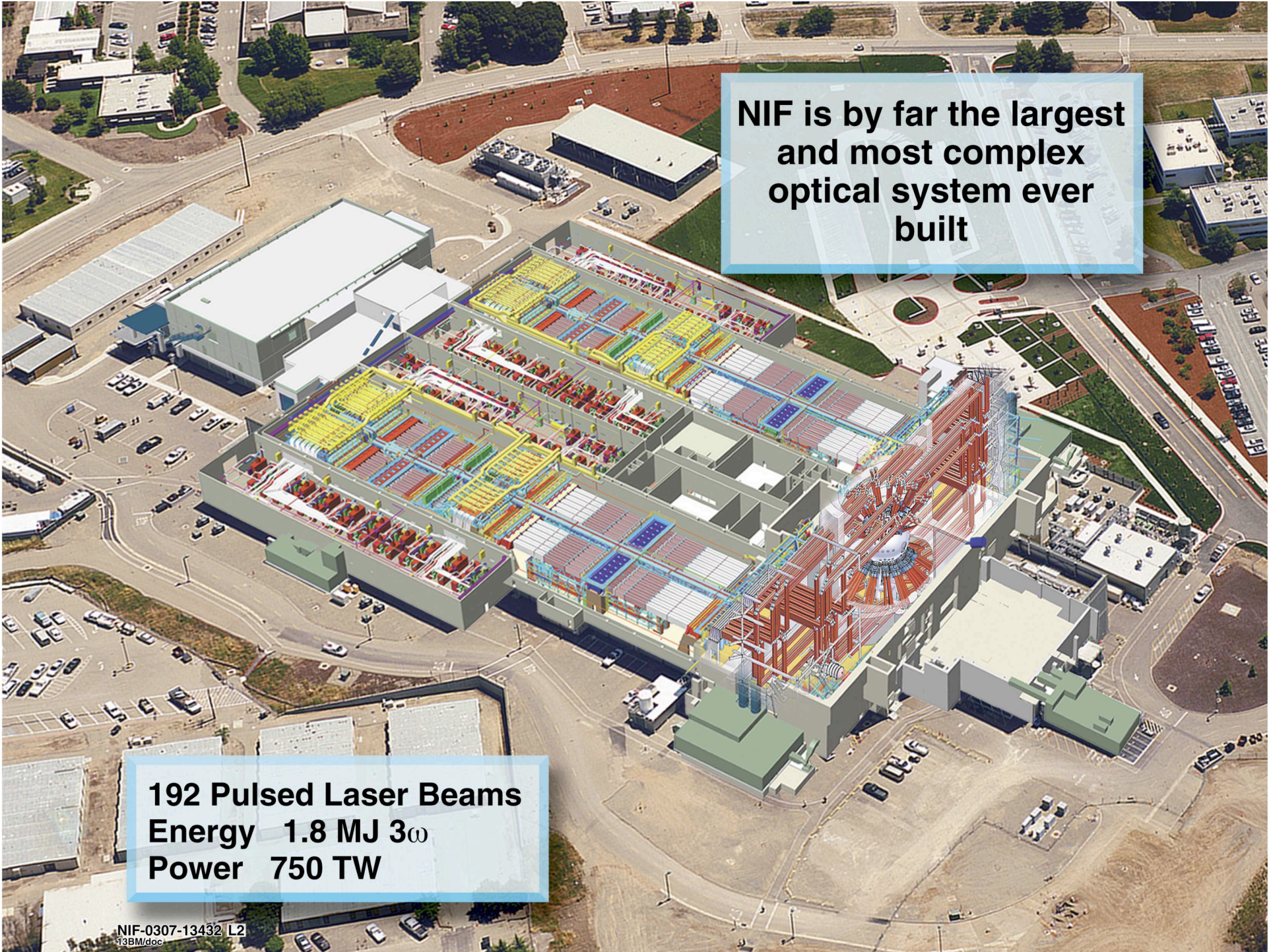
# OUTLINE

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- **Motivation/Application Domain**
- **NIF-ALE-AMR**
  - Basic ideas
  - Interface reconstruction
  - Hierarchical material models
  - Fragment modeling with void
- **Team Development**



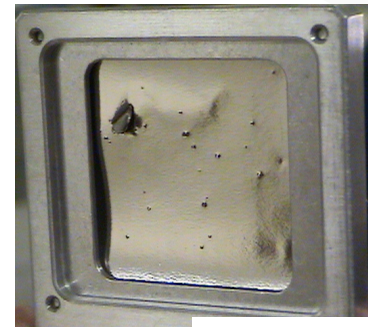
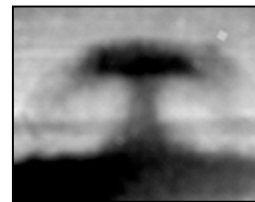
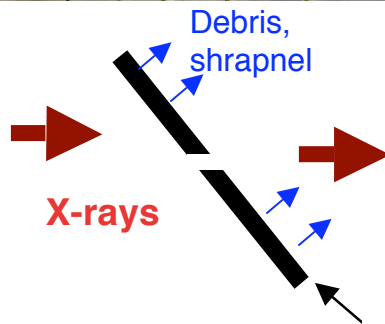
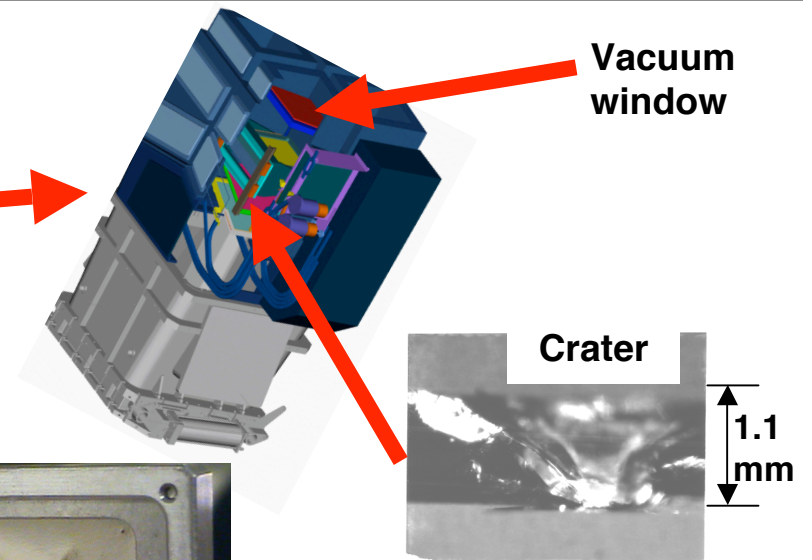
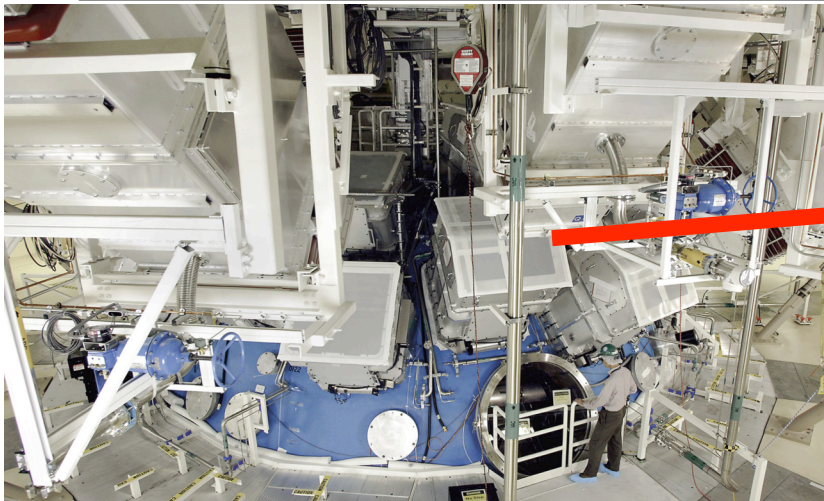
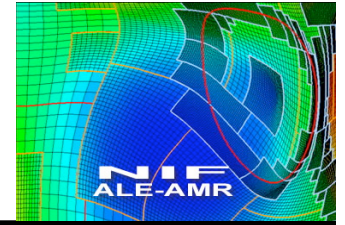


**NIF is by far the largest  
and most complex  
optical system ever  
built**

**192 Pulsed Laser Beams  
Energy 1.8 MJ  $3\omega$   
Power 750 TW**

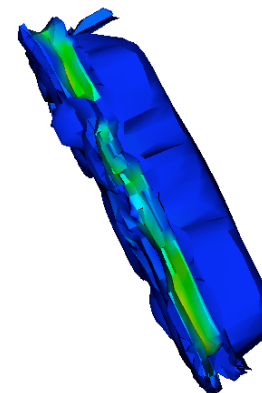
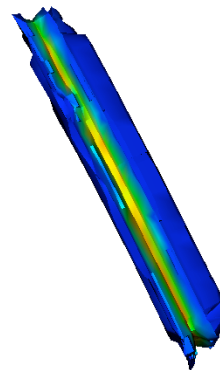


# Debris and Shrapnel damage to optics and diagnostics must be mitigated



Damage prior to tilting pinhole substrate

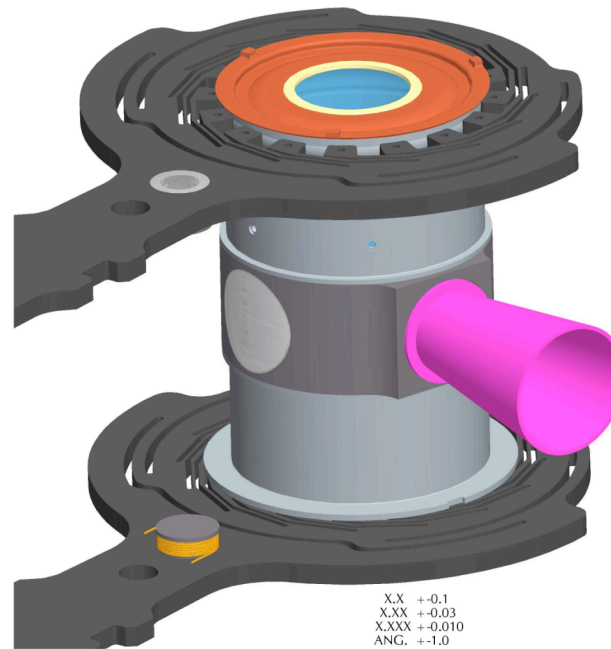
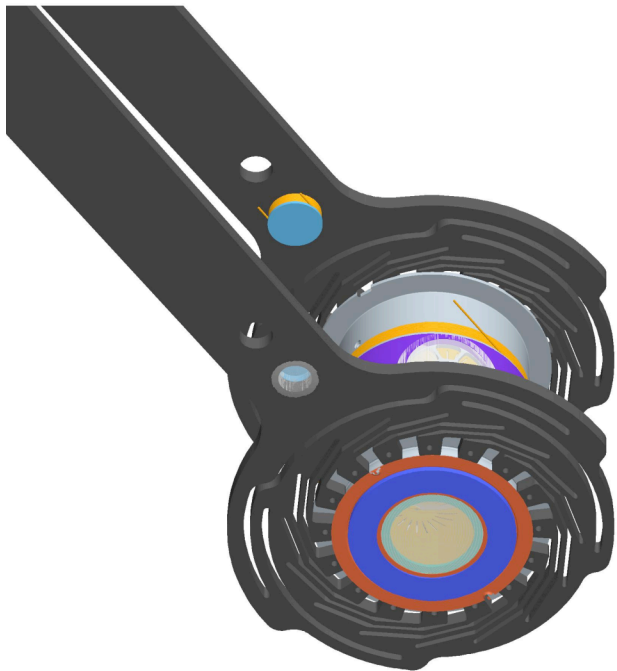
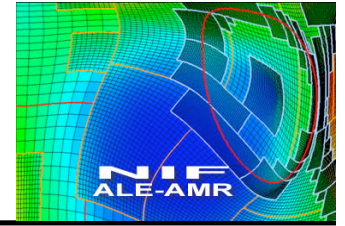
Already on NEL, simulations were important for mitigating diagnostic damage



Time progression of 3D foil simulation (density isosurfaces) shows Ta blow-off in normal direction



**Calculations must include the entire target structure, focus is outside the hohlraum**

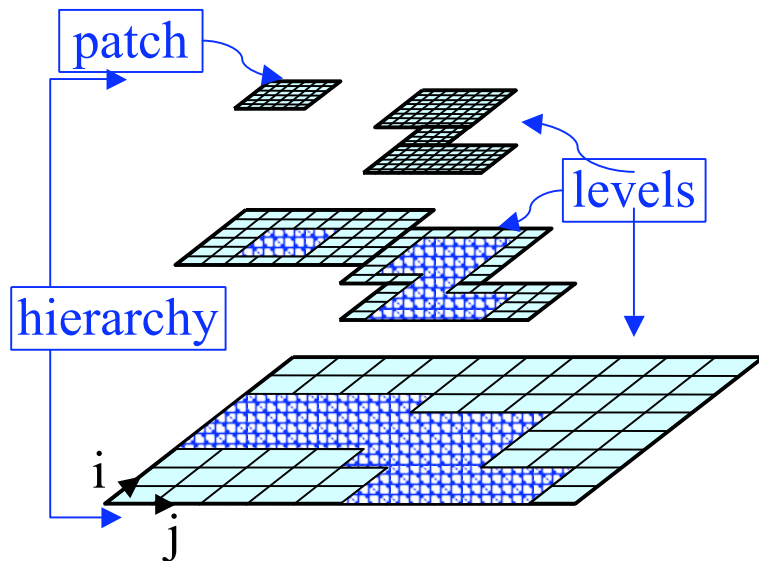
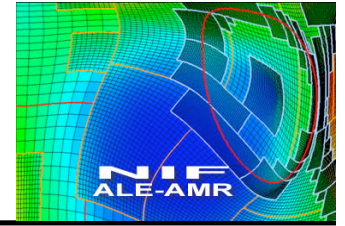


**AI Outer Cone on  
Keyhole target**

**Sample 96 Beam Campaign Targets**



# Model has ALE and Adaptive Mesh Refinement and hierarchical material models (HMM)



ALE + Structured AMR

## Spatial Resolution

Macro (mm - cm+)

Meso  
(100 $\mu$ m)

Micro  
( $\mu$ m)

## Material Model

Analytical  
Flow-Stress Models

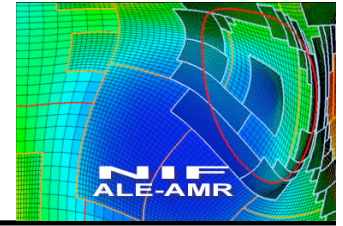
Polycrystal Models:  
Texture evolution and  
Moderate Number of  
Grains/Zone

HMM Model Application:  
AMR Spatial Resolution  
from Grain to Sub-Grain

Single-Crystal Plasticity  
(May include phase  
transformations)

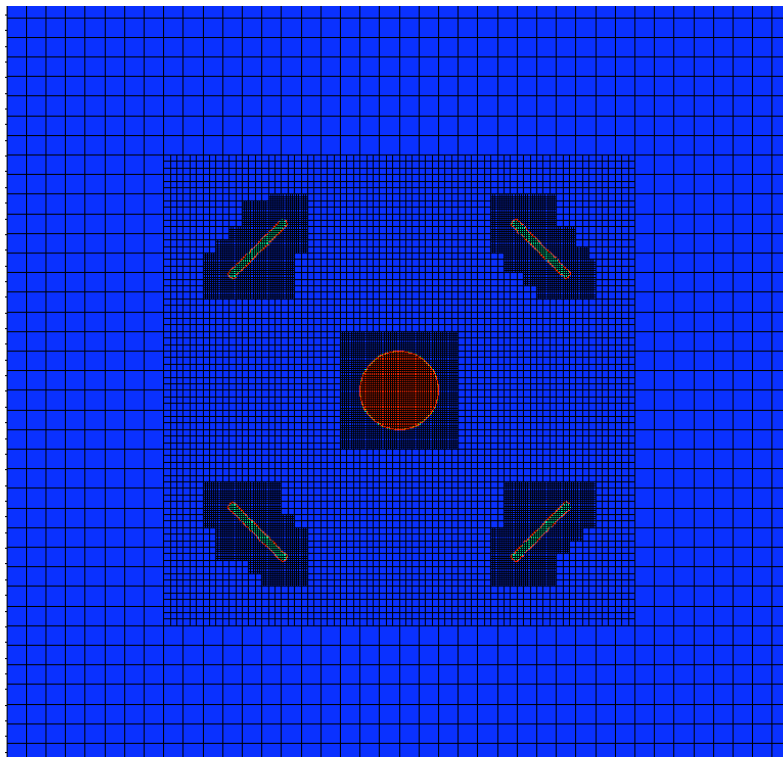


# Adaptive mesh capability is crucial for large range of scales and also enables HMM\*

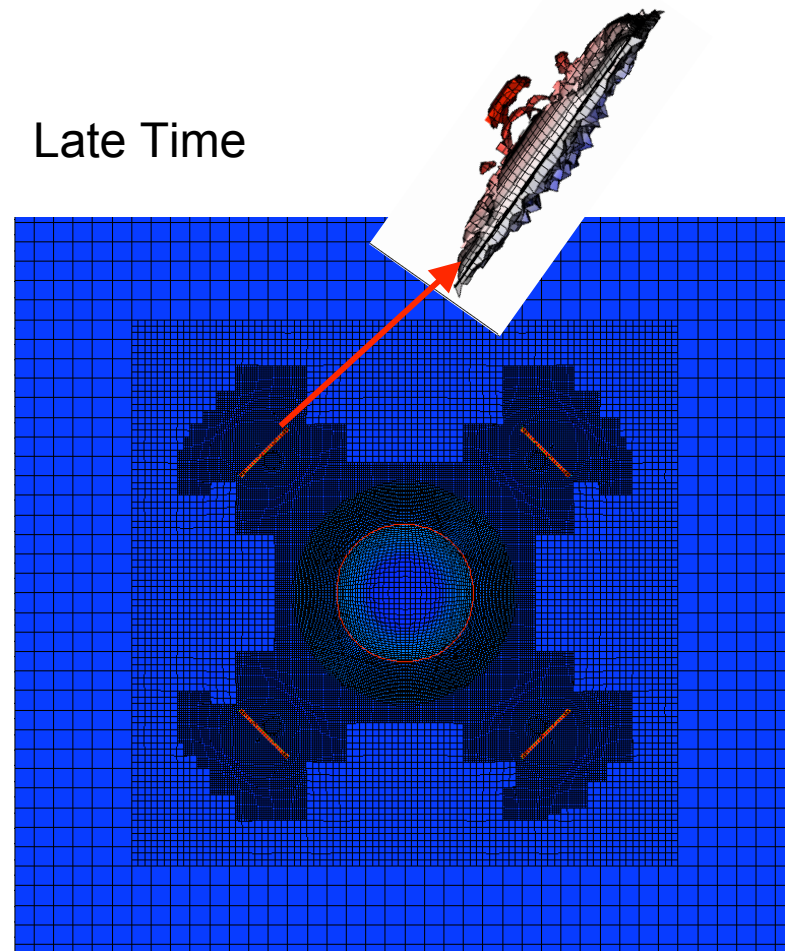


- Simulated target configuration with 4 shields surrounding energy source

Early Time



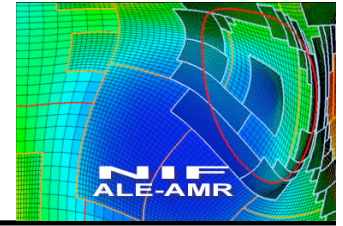
Late Time



\*HMM = Hierarchical Material Model

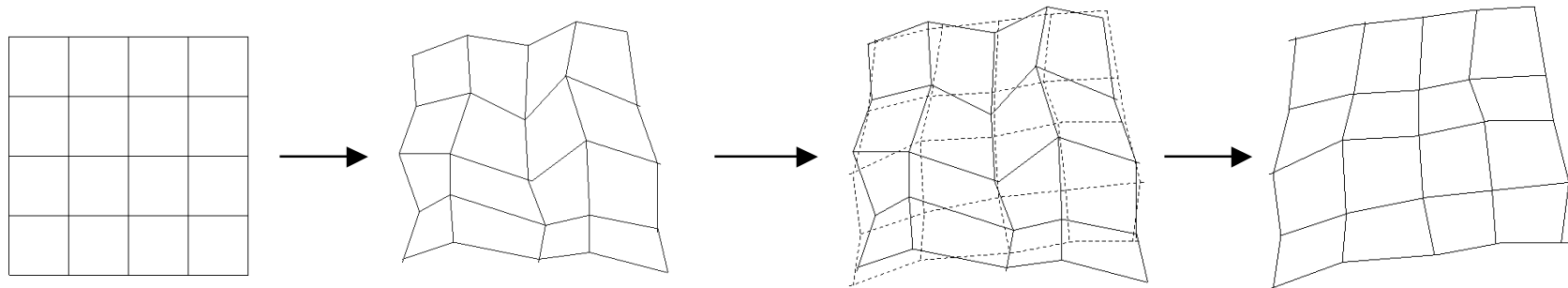
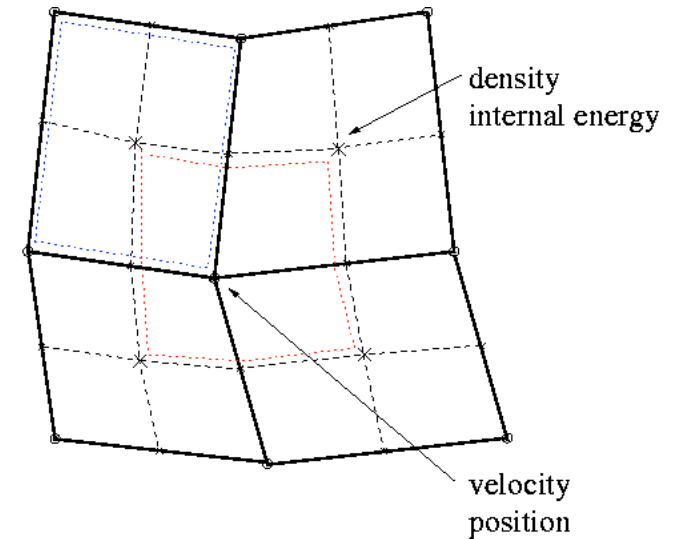


# The ALE+AMR structure is due to a methodology developed by Anderson and Pember



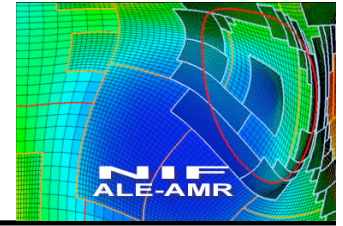
ALE approach is due to Wilkins (“HEMP”) -uses a moving staggered mesh and a three step computational cycle on a structured grid with staggered variables

- **Time step: Lagrange + Grid Relax + Remap**



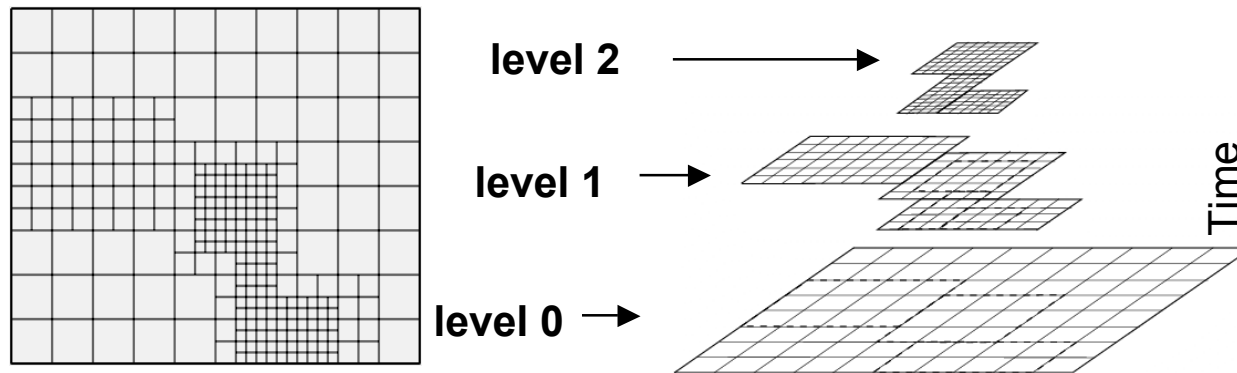


## Anderson and Pember designed a strategy for incorporating the AMR into ALE codes



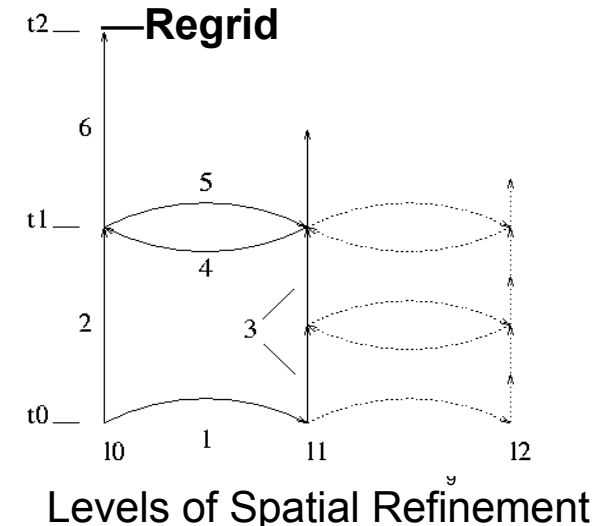
- Single-level methods + Interlevel transfer operators + hierarchy advance algorithms
- An added benefit is that the NIF-ALE-AMR code is automatically scalable based on its underlying use of the SAMRAI adaptive mesh refinement framework
- Another benefit is that we are able to use different material models at different levels

### •Spatial refinement



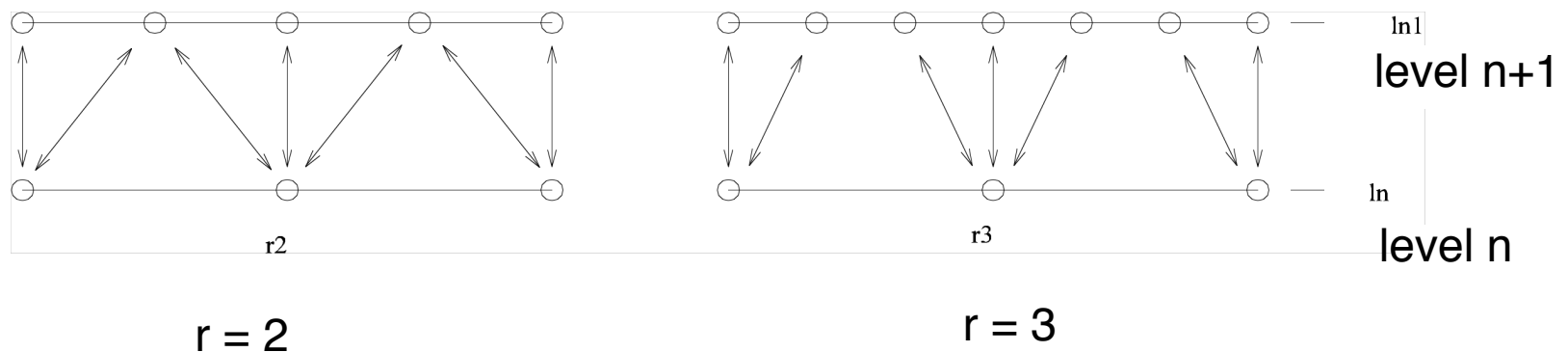
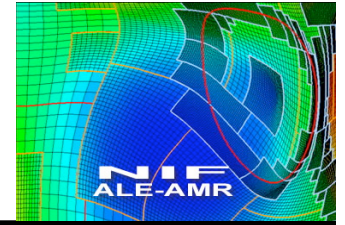
### •Hierarchy time step:

- Advance coarse level
- Advance fine level
- Synchronize levels
- Regrid





**Refinement is unlimited, but practically we keep  
~ 3-4 levels. Ratio of 3 required for invertibility**

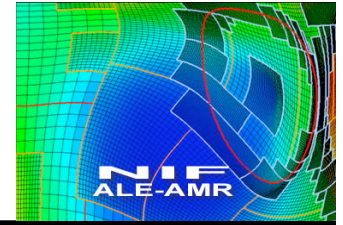


A  $1:r^d$  logical correspondence between *both* cell and nodal quantities is only possible with *odd* refinement ratios.

This makes invertible pairs of operators simple to construct.



# Use of SAMRAI Library yields a scalable code and hides details of MPI and optimization



## OLD Algorithm inefficiencies:

Acquiring/storing global mesh description

Operations and loops on global meta data

Many algorithms scaling like  $O(N)$ .

All algorithms require global mesh description

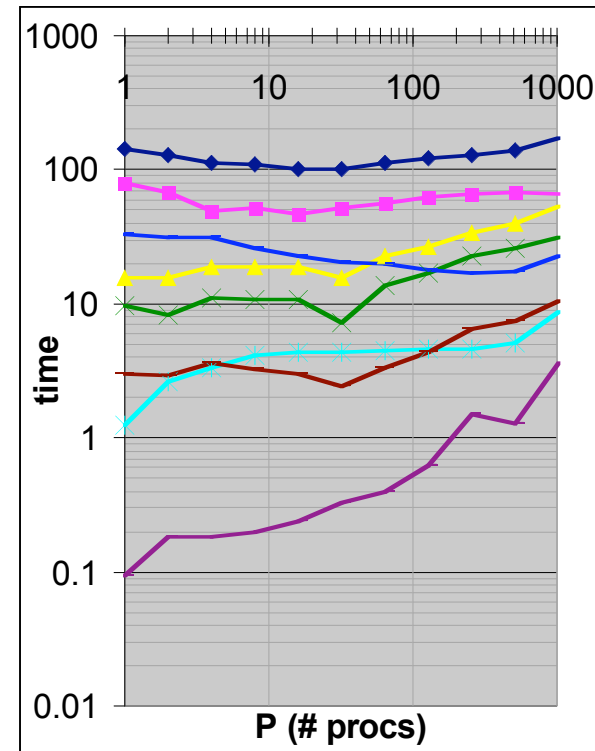
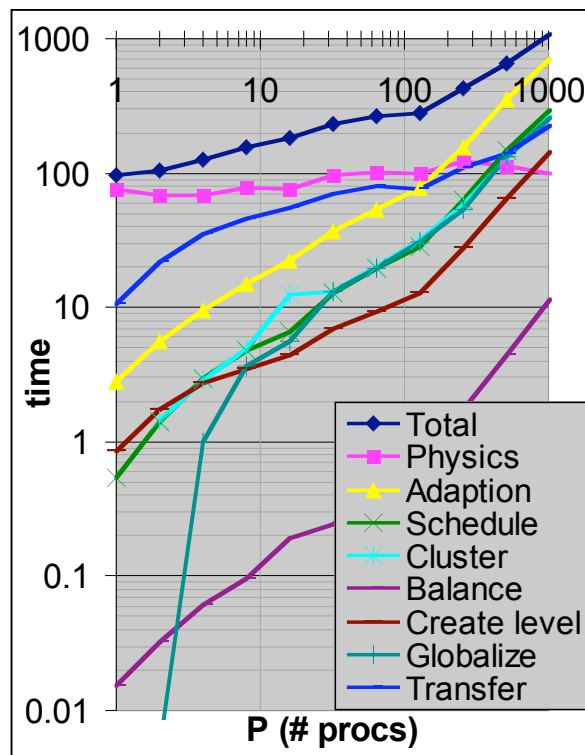
Most **NEW** algorithms scale close to ideal ( $N/P$ )

Rises in curves are due to

Initializing long arrays

Sequentializing patch indices

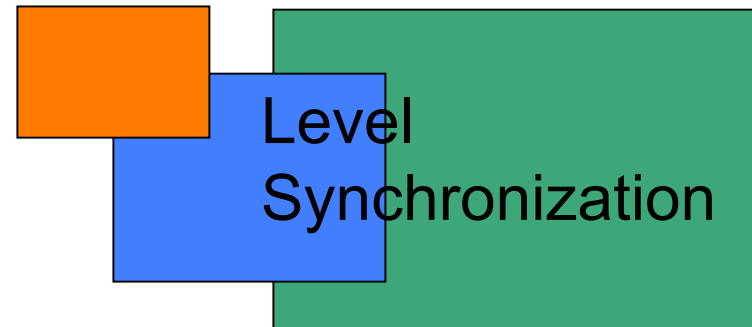
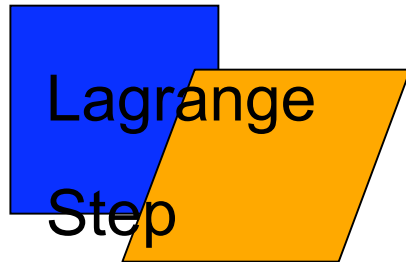
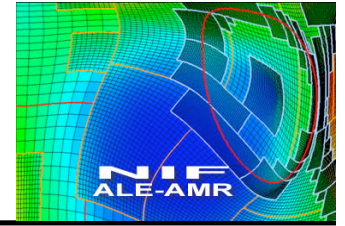
Physics scales really well -- so adding more physics tends to increase scalability



See e.g., Gunney, et. al., "Parallel Clustering Algorithms for Structured AMR", J. Parallel and Distributed Computing, in press.



# **NIF's ALE-AMR has sub-scale physics and fragmentation models for anisotropic materials**

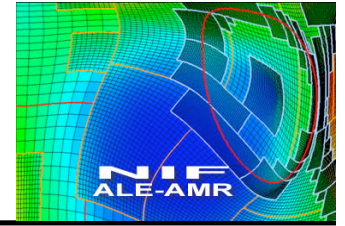


- Advance all levels (Lagrangian)
- Determine new mesh configuration: Relaxed (ALE) or Original (Eulerian)
- Remap (Advection) to new mesh
- Synchronize levels and Coarsen/Refine (Regrid) as necessary

- Determine new volume fractions, evaluate stress, accelerations, material failure, etc. Weight by bulk modulus/shear modulus as needed. Important for e.g., problems with air/solid interfaces.
- Consider material topology in advection
- Reconstruct appropriate material interfaces during coarsening and refinement



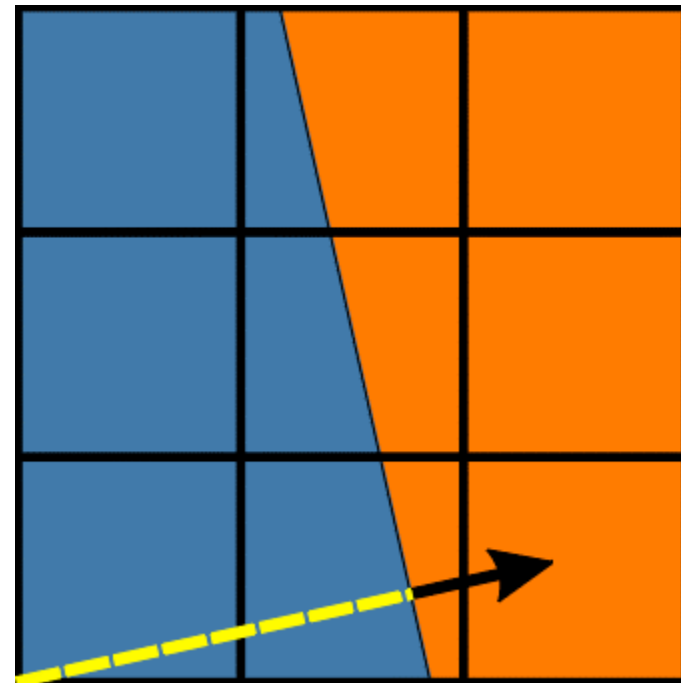
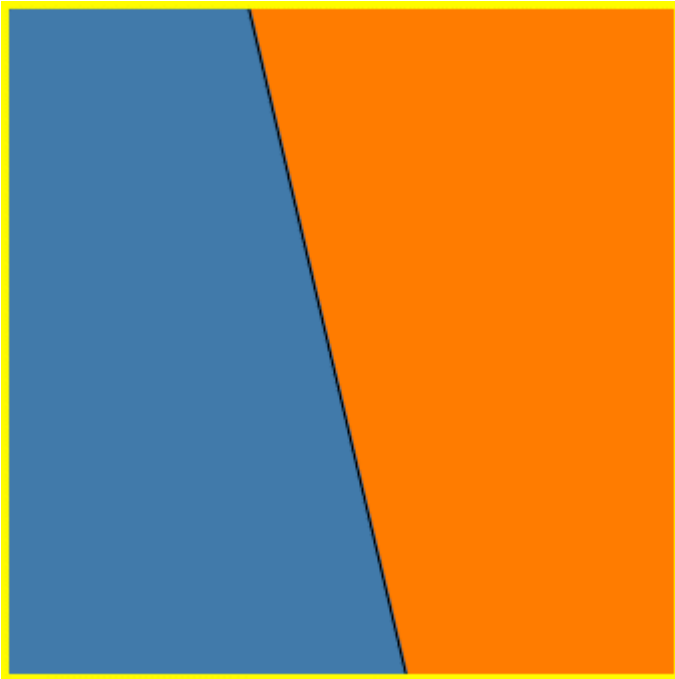
# AMR: Coarsening is easy, Refinement requires explicit interface reconstruction



- Sum of volume fractions

$$V_f^c = \sum_i V_{f,i}^f V_i^f / \sum_i V_i^f$$

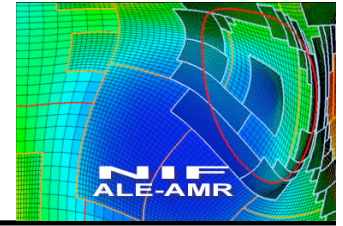
- Orientation uses  $V_f$  's of neighboring cells
- Solve for location of interface
- Assign refined  $V_f$  's



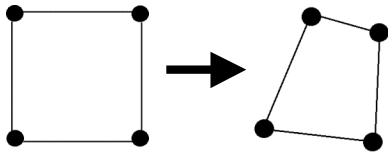
For details, see Masters, et al., IFSA Proceedings 2007.



# Failure implementation can use a variety of models including Johnson - Cook



Deformation from  
Lagrange step



Compute  
Strain rates

$$\dot{\epsilon}_{ij} = \frac{1}{2} \left( \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right)$$

Compute Stress with  
Johnson-Cook Model

$$\sigma = [A + B(\epsilon^p)^n][1 + C \ln(\dot{\epsilon}^p)][1 - \left(\frac{T - T_{room}}{T_{melt} - T_{room}}\right)]$$

Accumulate Damage with Johnson-Cook  
Failure Strain model

$$\epsilon^f = [d_1 + d_2 e^{d_3 \sigma^p / \sigma^e}][1 + d_4 \ln(\dot{\epsilon}^p)][1 + d_5 \left(\frac{T - T_{room}}{T_{melt} - T_{room}}\right)]$$

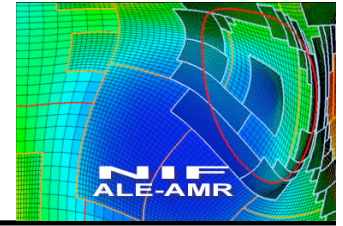
$$D = \sum \frac{\Delta \epsilon^p}{\epsilon^f}$$

For  $D > 1$  material in cell fails

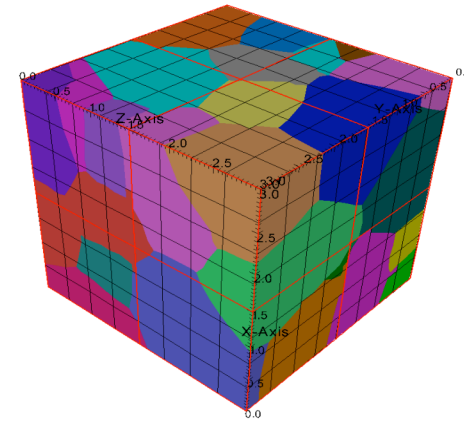
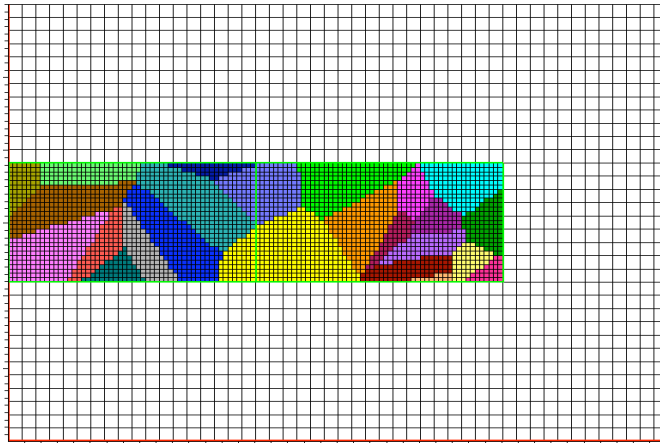
For details, see Fisher, et al., IFSA Proceedings 2007.



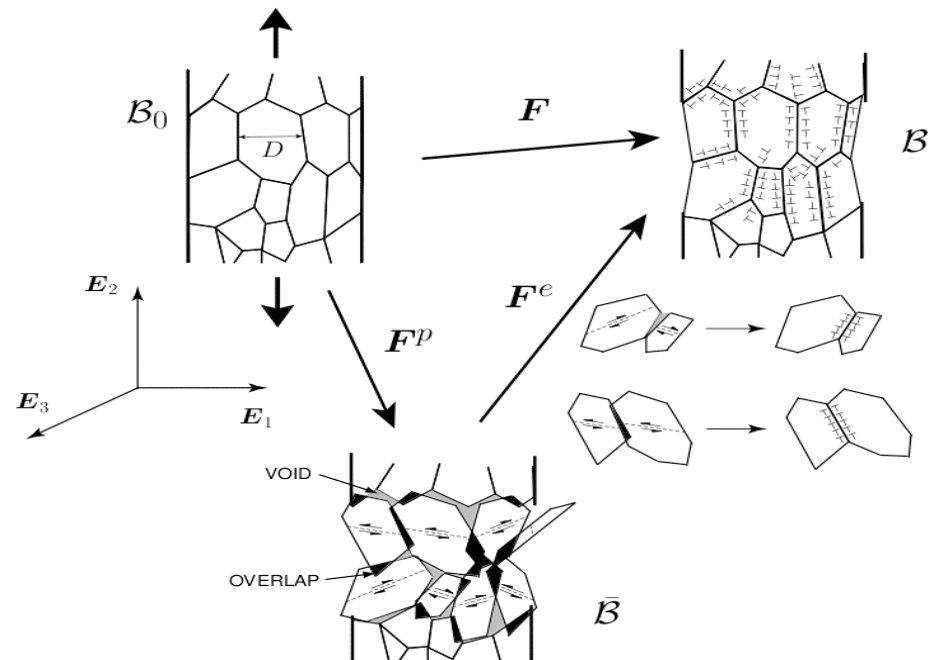
# With AMR/HMM at finest scales we can introduce anisotropic models like single and polycrystals



## Polycrystal Model on bar test problem with AMR mesh

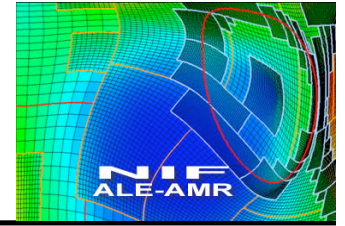


- Voronoi method to generate polycrystals within AMR infrastructure is implemented
  - Set up the voronoi polycrystals at the finest level.
  - Johnson-Cook model is run at levels 0 and 1 and the Single Crystal Plasticity is at level 2.

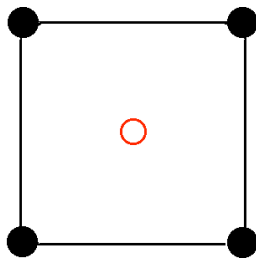




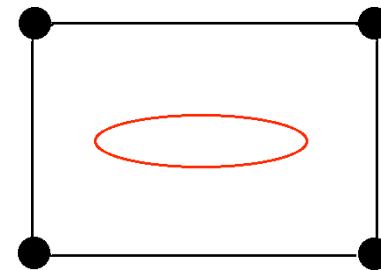
## Part of the failure model allows fragment formation



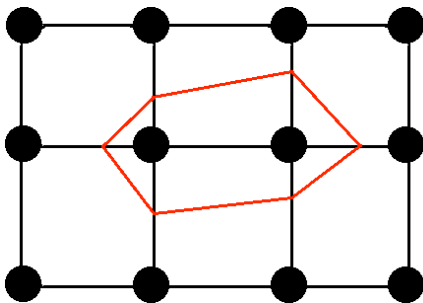
Upon failure a small volume fraction of void is introduced into the cell



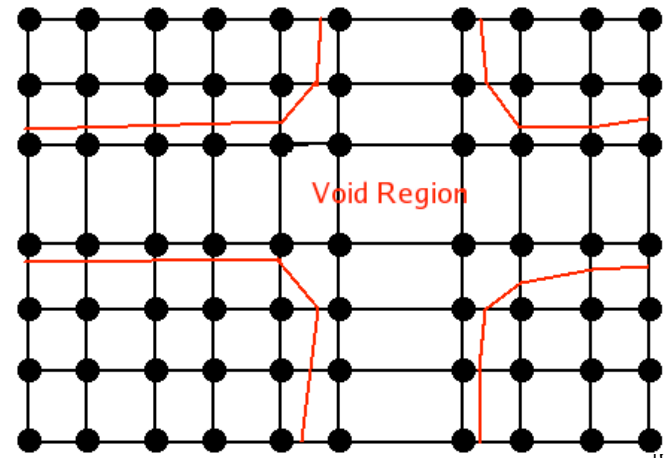
If the cell continues to grow the void enlarges to meet that growth



Volume fraction interface reconstruction allows voids to coalesce to form cracks

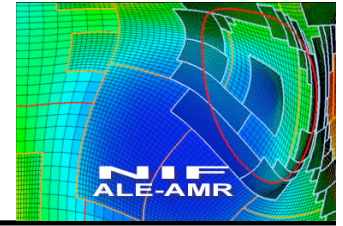


Cracks can grow large enough to span across cells allowing fragment formation

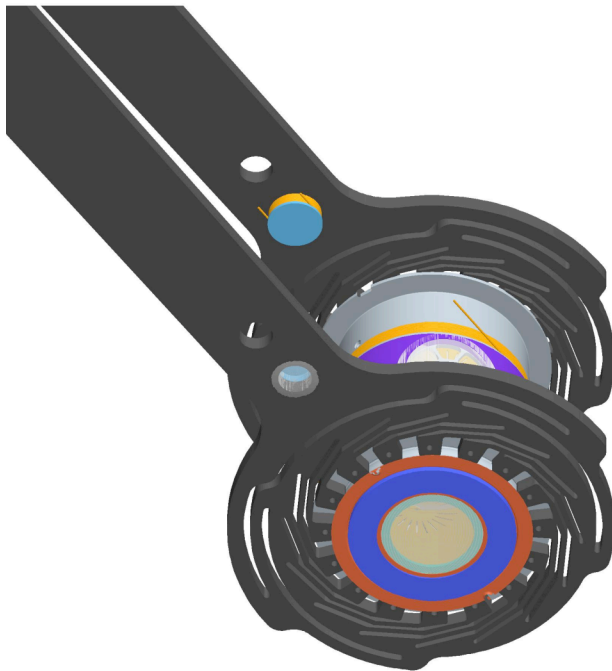




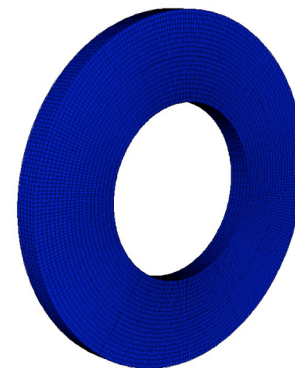
**All calculations should include the entire target structure, focus is outside the hohlraum**



**Johnson-Cook model fragment size prediction of NIF target cooling rings**

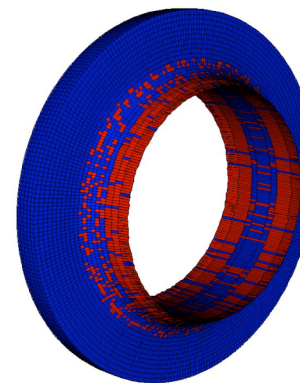


**Target**

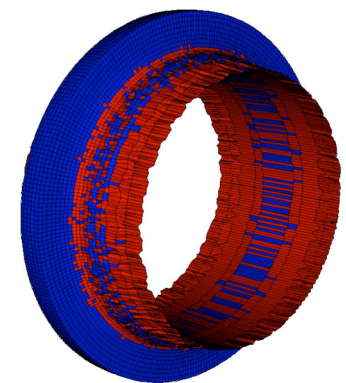


$t = 0 \mu s$

$R_{inner} = 2 \text{ mm}$   
 $R_{outer} = 4 \text{ mm}$   
Width = 0.5 mm



$t = 0.5 \mu s$



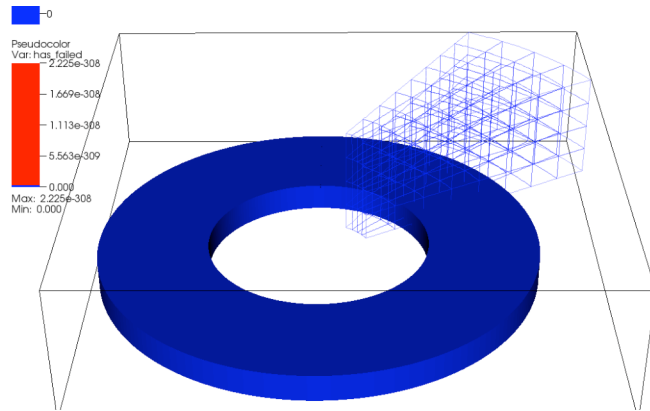
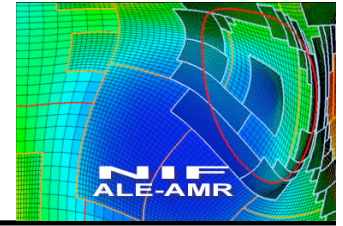
$t = 1 \mu s$

**Low resolution scoping simulation shows direction of fragment blow off. High resolution simulation on next slide shows fragment formation.**

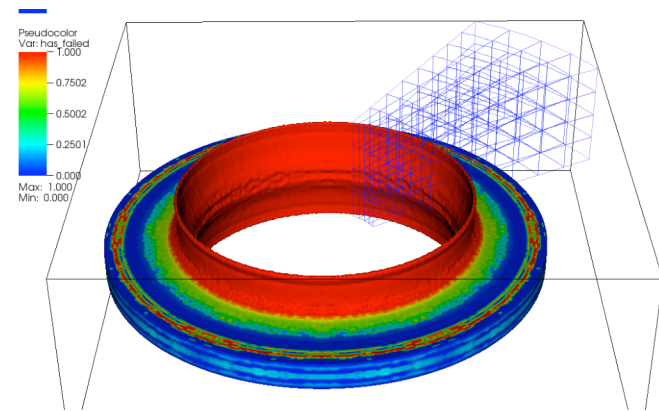
**Red indicates failure**



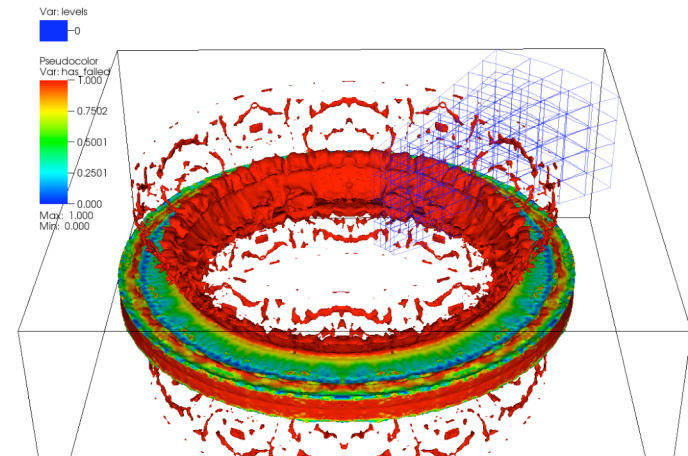
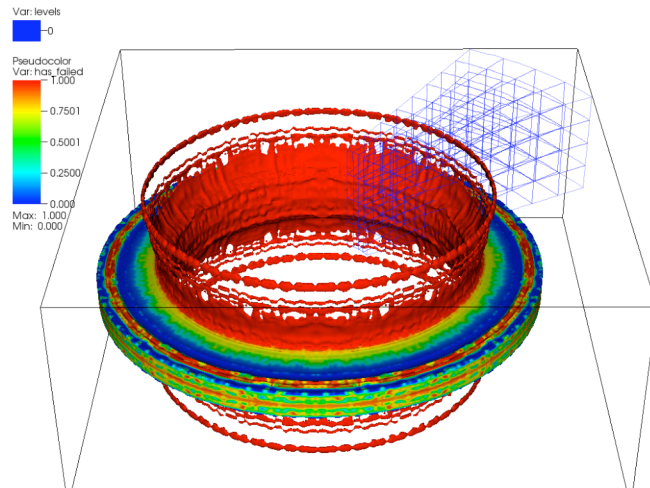
# Cooling Ring Fragmentation Simulation shows spall-ring formation and predicts fragment size



Blue boxes show computational domain and initial parallel processor decomposition (128 Procs) -- one domain per cube



Color Bar denotes percentage of failure in a zone: blue -- no failure, red: zone completely failed



The ring disintegrates into spall planes or rings that disperse along the hohlraum axis. Because the zones have failed, the fragments get smaller as they propagate outward. No large chunks are formed -- contrast with upcoming copper notch simulation on upcoming slides.

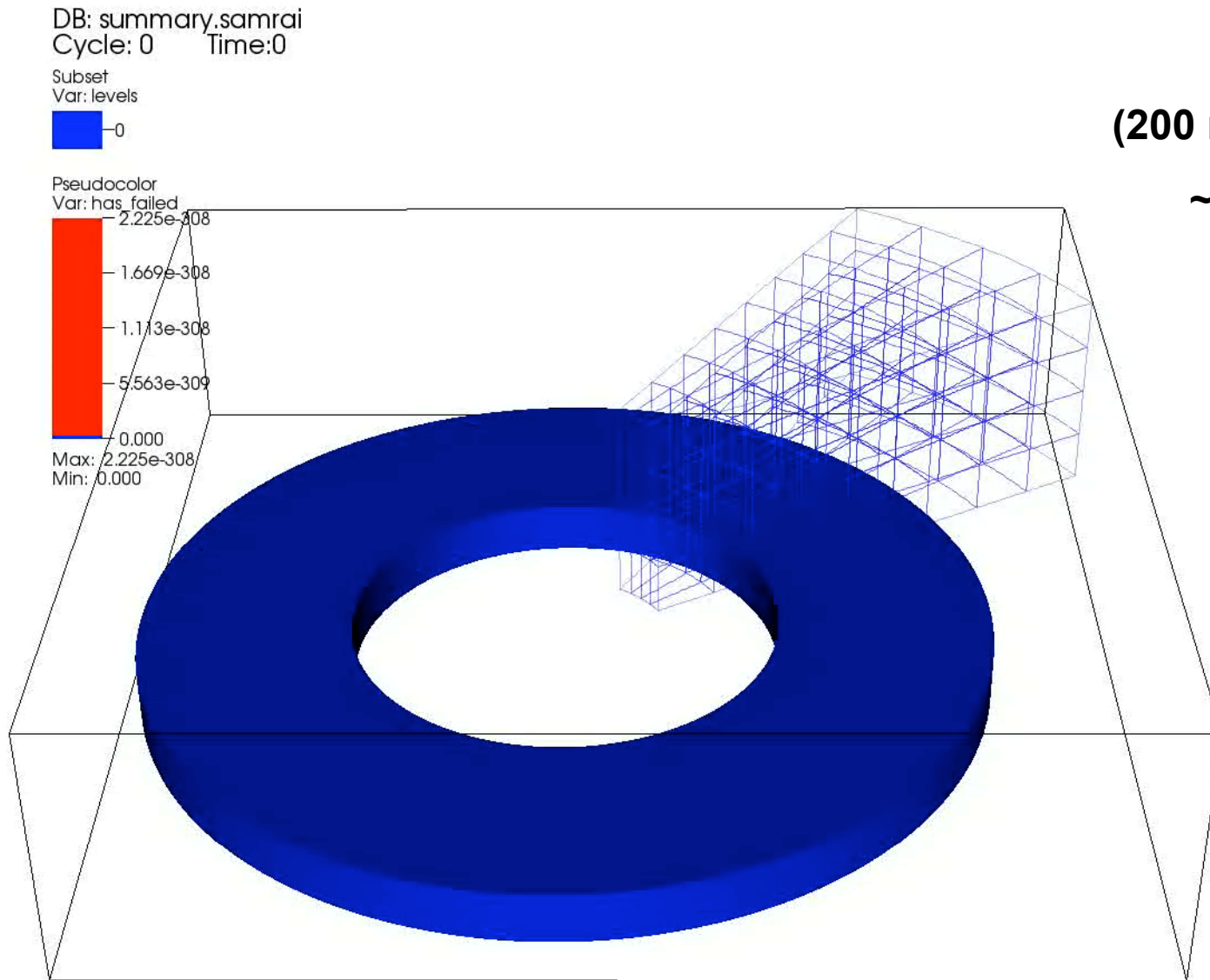


**128 Procs**

**960,000 zones**

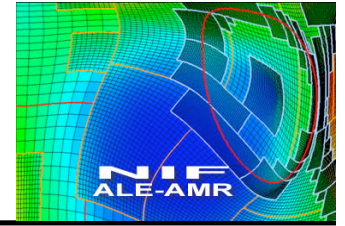
**(200 radial, 60 theta, 80 z)**

**~7500 zones/proc**





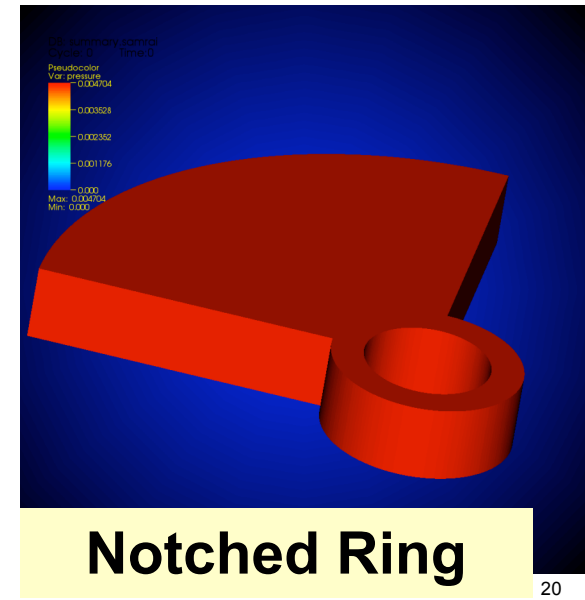
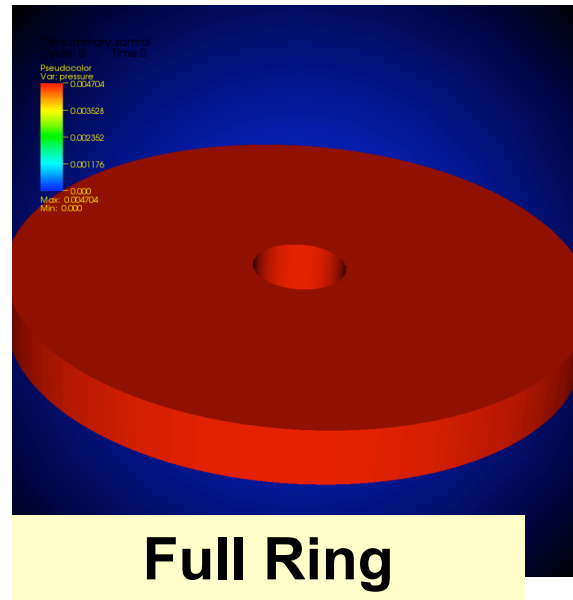
# Problem: Copper cooling rings causing damage on Omega



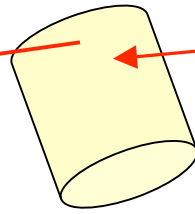
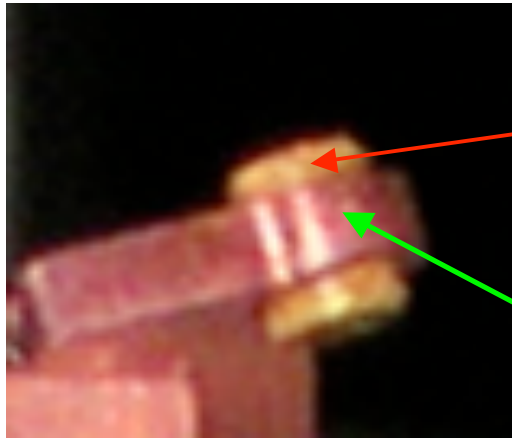
## Full Ring and Notched Ring Designs

Possibly more damage with  
Notched Ring

## Explanation: Simulation



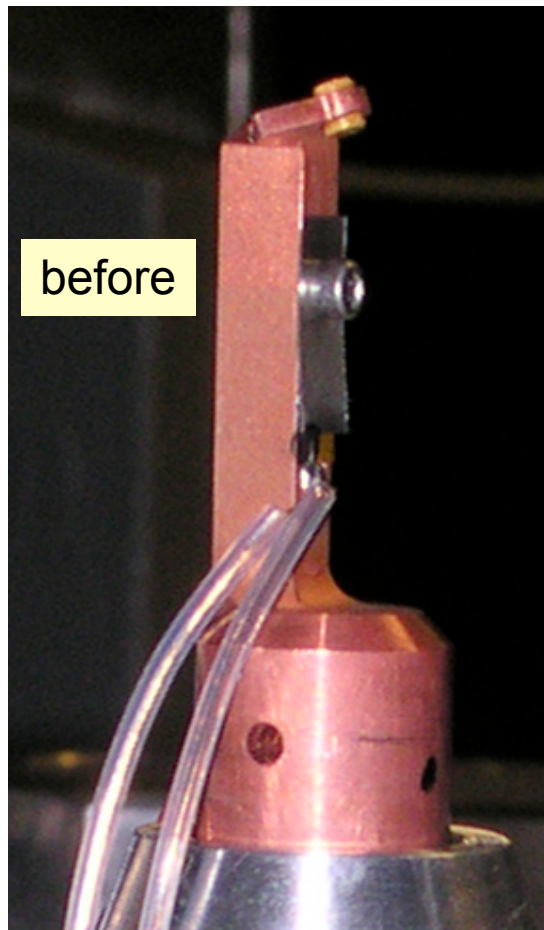




Cu

Hohlraum surrounded by Cu notched cooling ring structure rendered 10 debris shields inoperable on Omega.

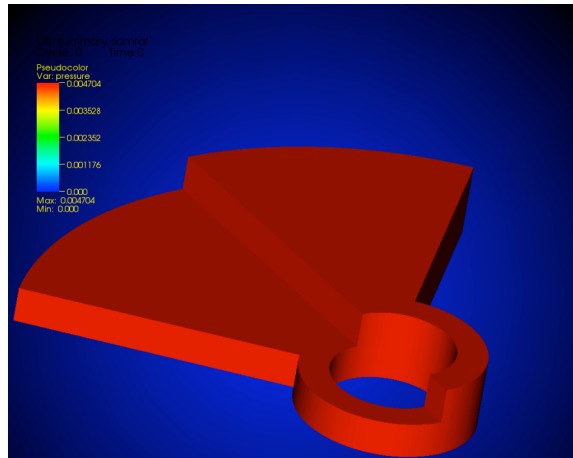
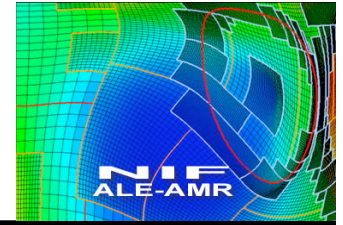
- 10 debris shields were damaged to the point that the scattered light caused them to fail transmission specifications
- 1 of these debris shields, 5 mm thick, had a chip that went through the entire thickness
- loss in transmission from these 3 shots was on average 3% over all 60 debris shields
- To put this in perspective we normally see ~6% loss over a full month



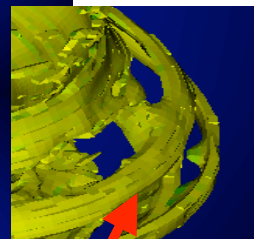
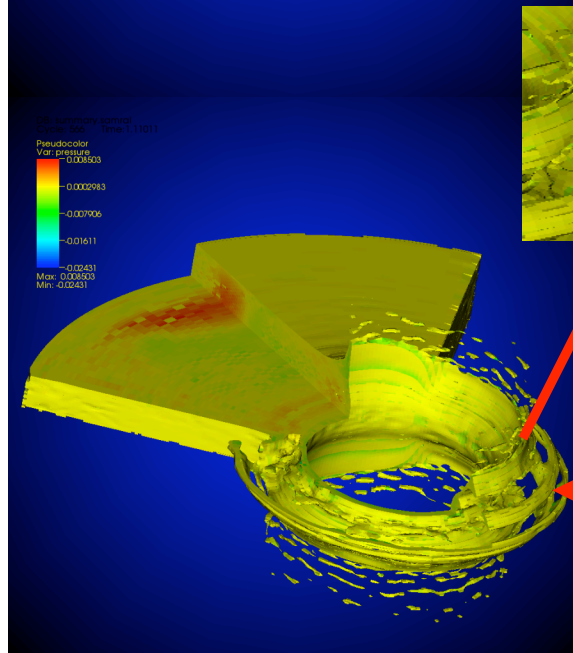
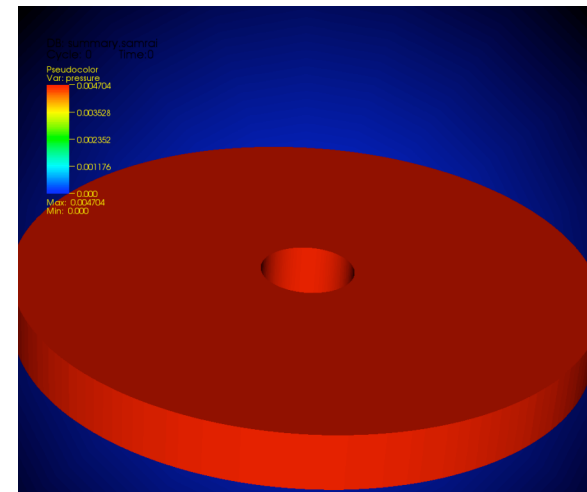
Simulations explain why this was not a good solution to debris problem.



# Simulation explains that notched ring breaks into larger pieces instead of small spall planes/rings

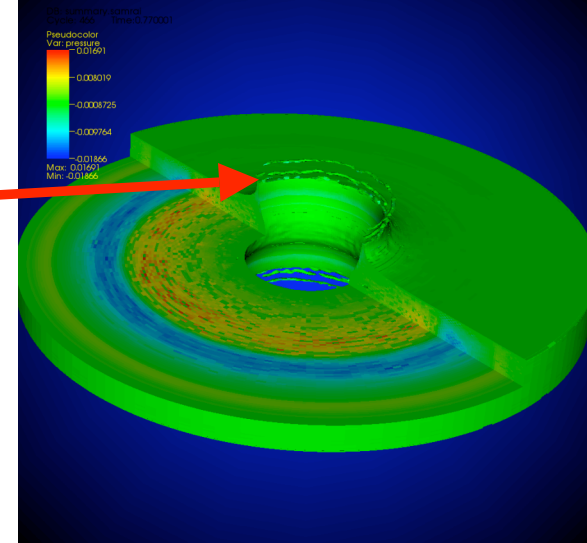


Note: “step” in target is not physical -- just to show interior of simulation.



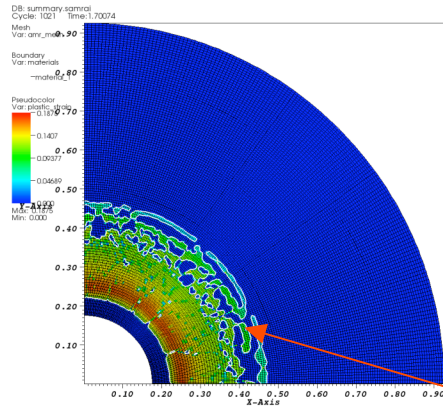
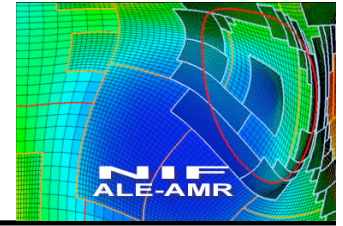
FORMATION OF SMALL SPALL PLANES

FORMATION OF LARGE DAMAGING PIECES IN THIS REGION



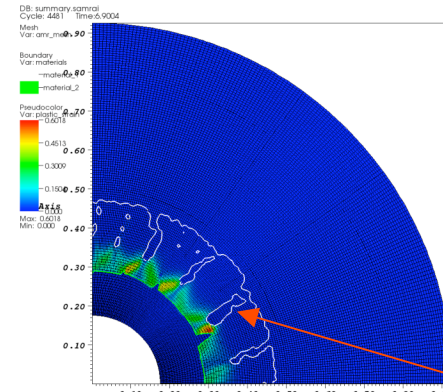


# Verification involves comparison with LS-DYNA. Different loading yields different behaviors.



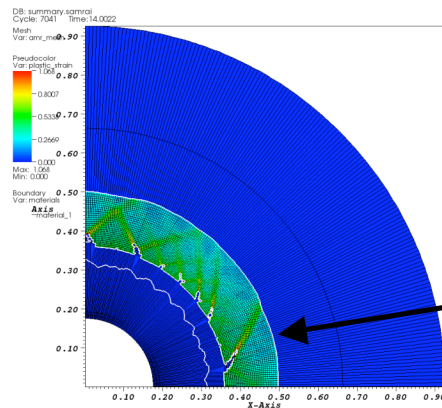
- ALE-AMR
- Eulerian
- impulsive loading
- w/ tensile failure
- mix fracture

Due to impulsive loading

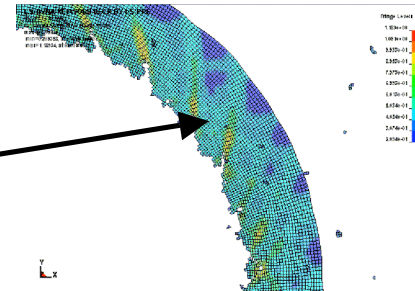


- ALE-AMR
- Eulerian
- pressure loading
- w/ tensile failure
- mix fracture

Tensile failures



- ALE-AMR
- Lagrangian
- pressure loading
- no tensile failure
- cell fracture

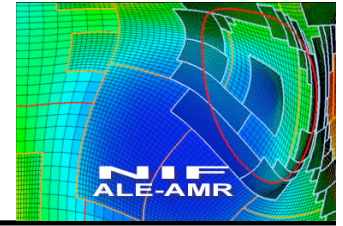


- LS-DYNA
- Lagrangian
- pressure loading
- no tensile failure
- cell fracture

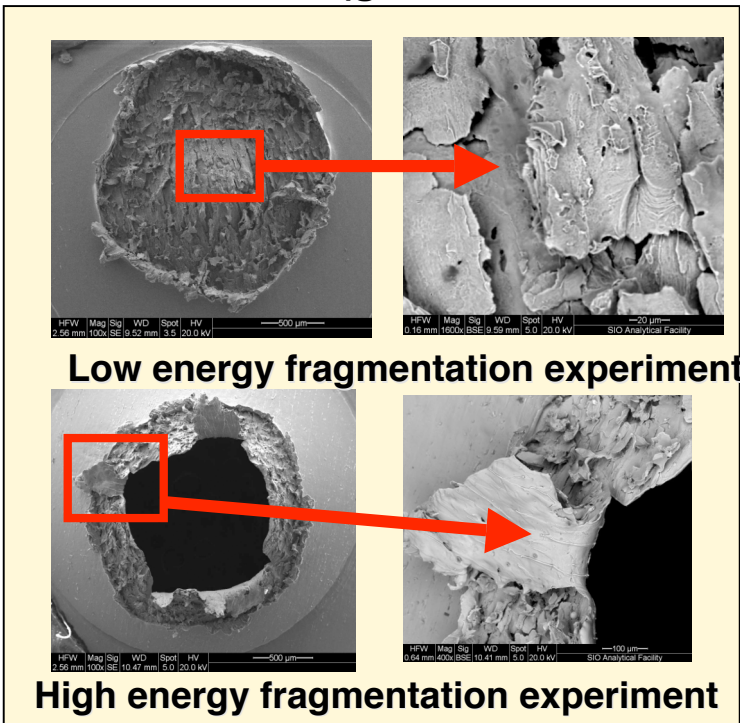
Pressurized void loading (less impulsive) gives a good match to LS-DYNA.  
ICF experiment is a more impulsive load from the expanding hohlraum.



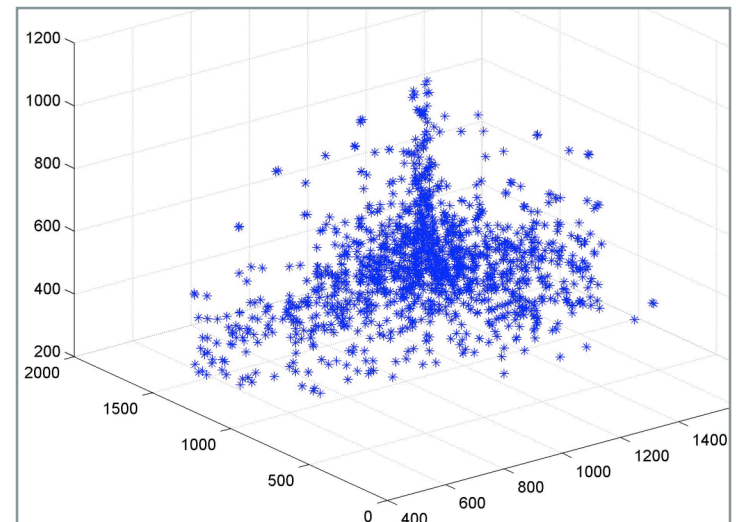
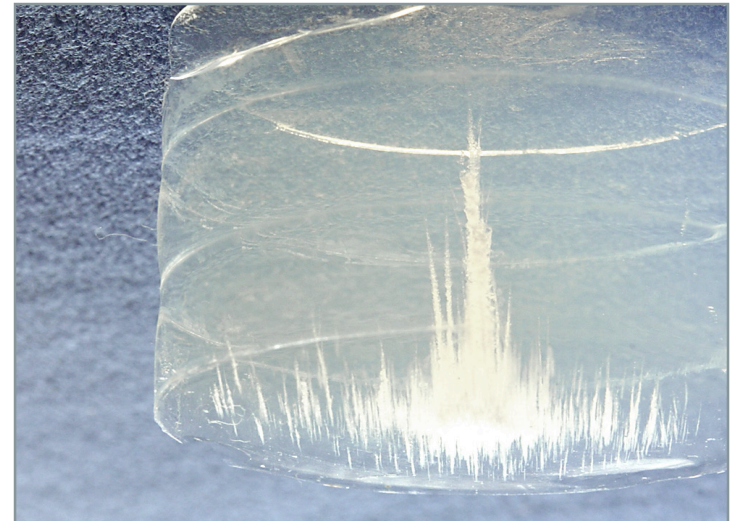
# Analysis of dedicated laser fragmentation experiments on Janus is in progress



Since targets are small ( $\sim 1$  cm), size scale of targets is within a few orders of magnitude of the microstructure (grain sizes  $\sim 10$  microns)

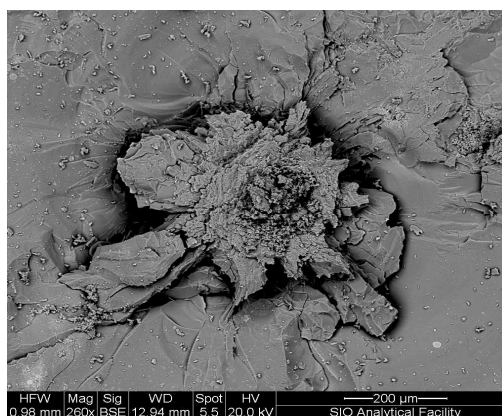
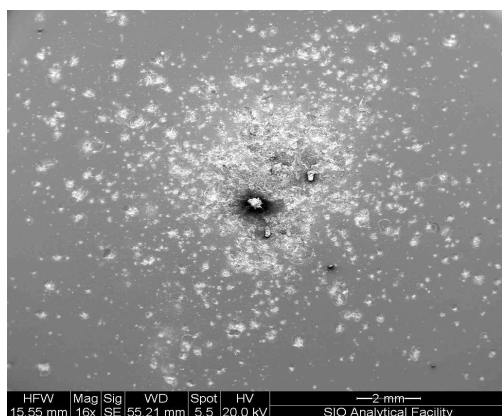
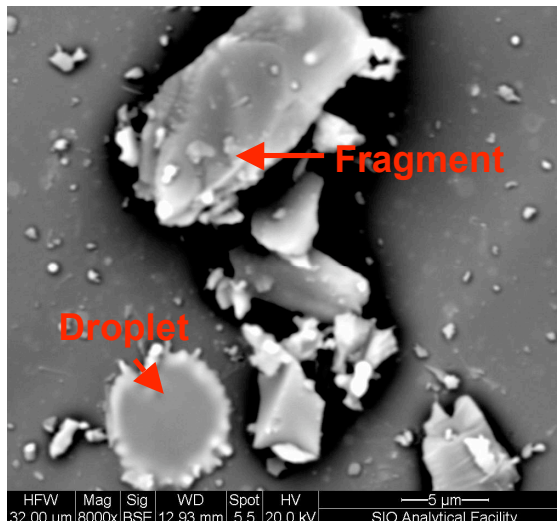
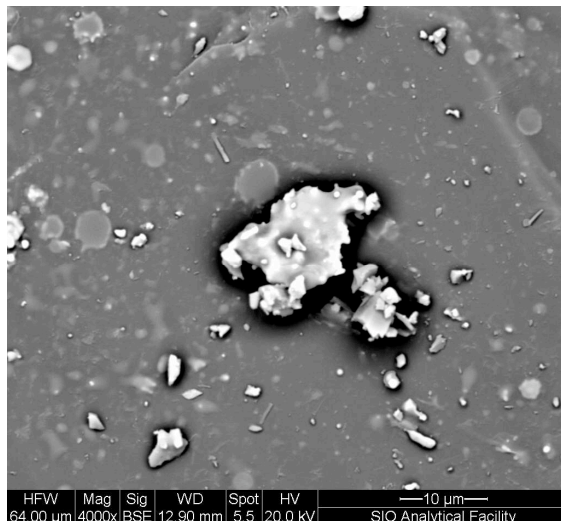
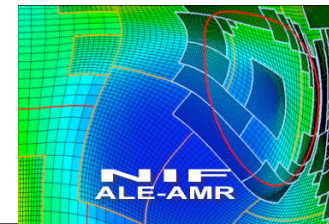


The scale of targets provides a unique test bed for multi-scale simulations





# Janus shots on glass are analyzed to distinguish fragments and liquid debris

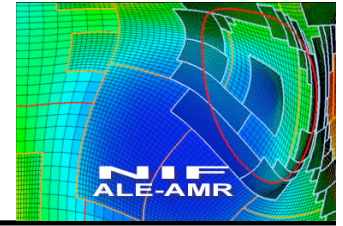


Validation includes predicting state from glass (liquid/solid) as well as statistical comparison of fragment sizes and velocities from aerogel collection

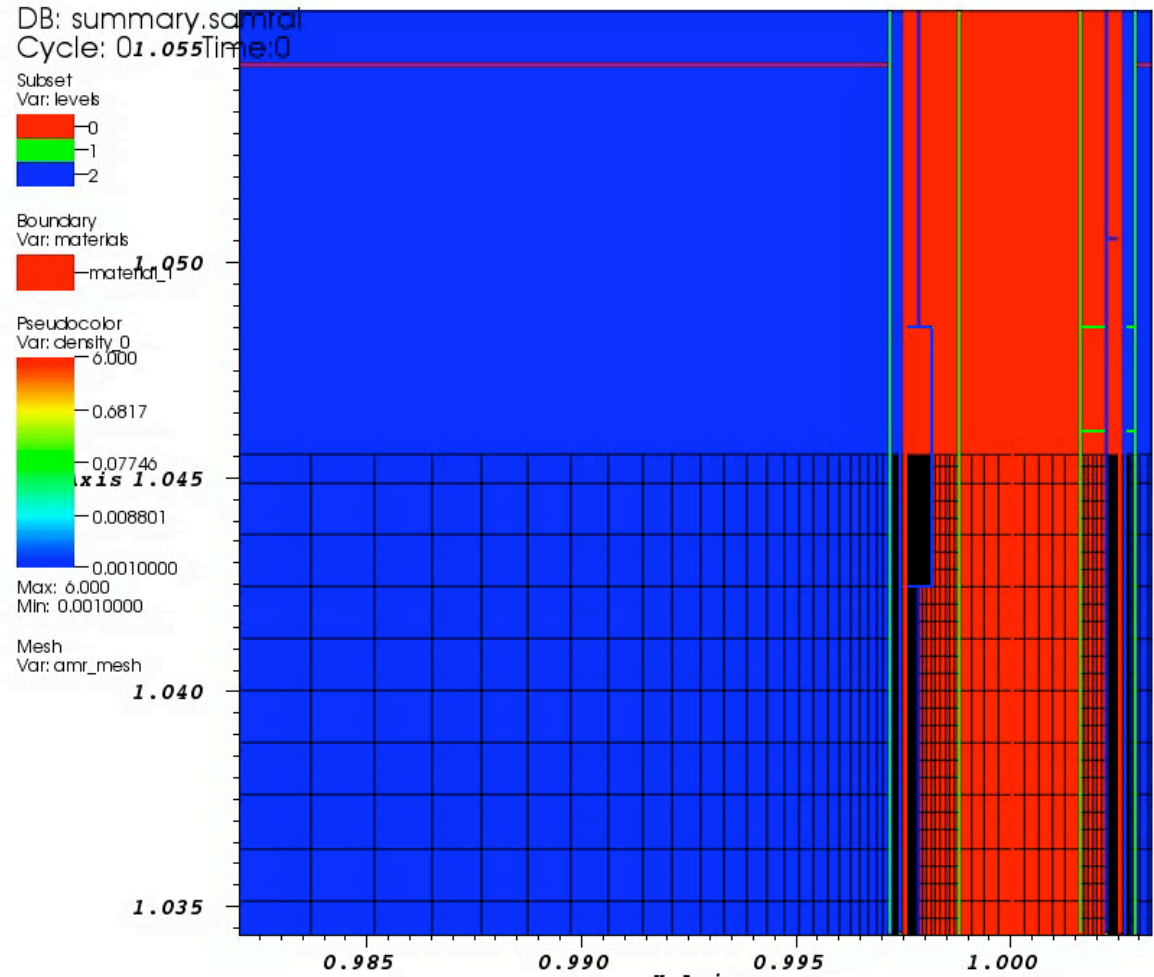
Upcoming Janus shots will have specially-made large single crystal vanadium to vary input to crystal plasticity model



## Thin plate problem shows levels of refinement

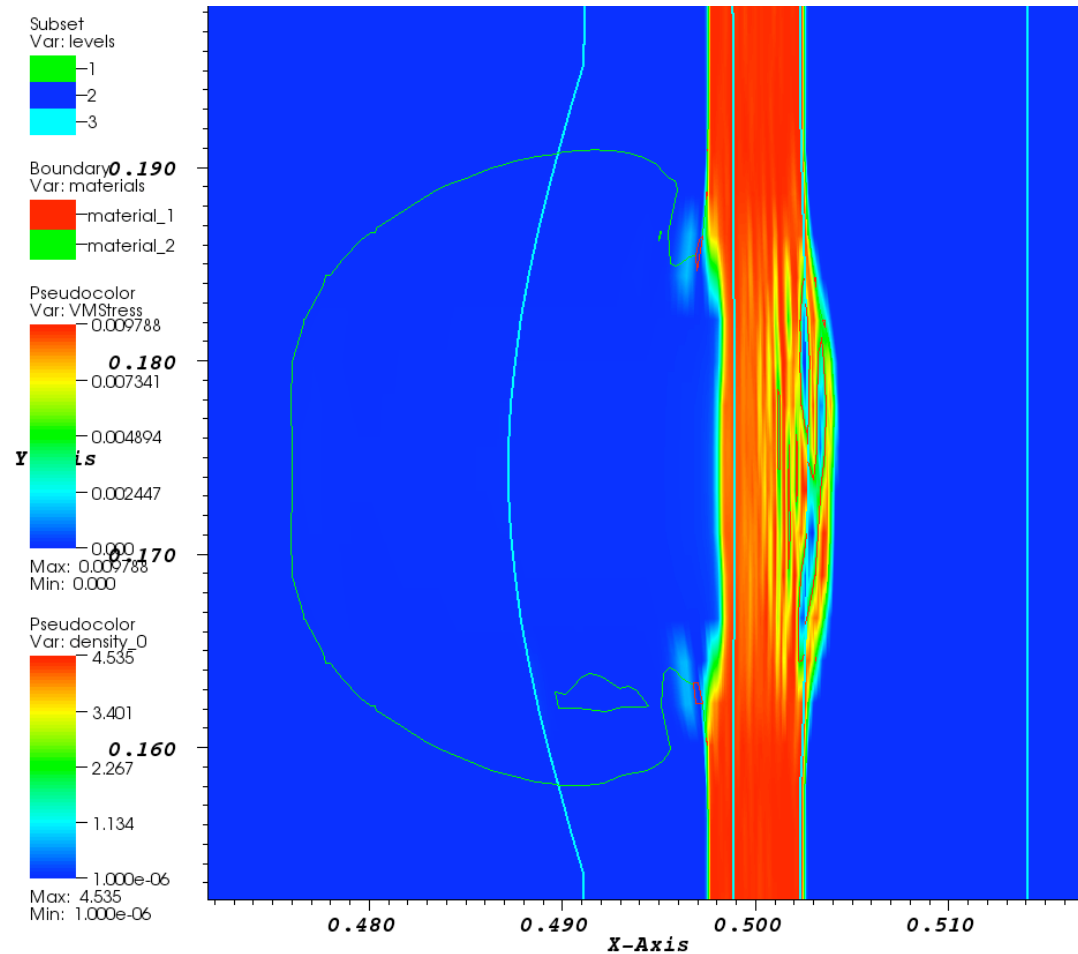
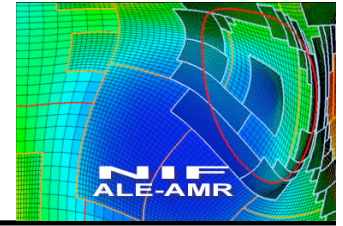


- Shooting very thin foils puts us close to the microstructural level.
- Problem is taxing for any code. Ability to run both Lagrangian and adaptively meshing Eulerian is critical



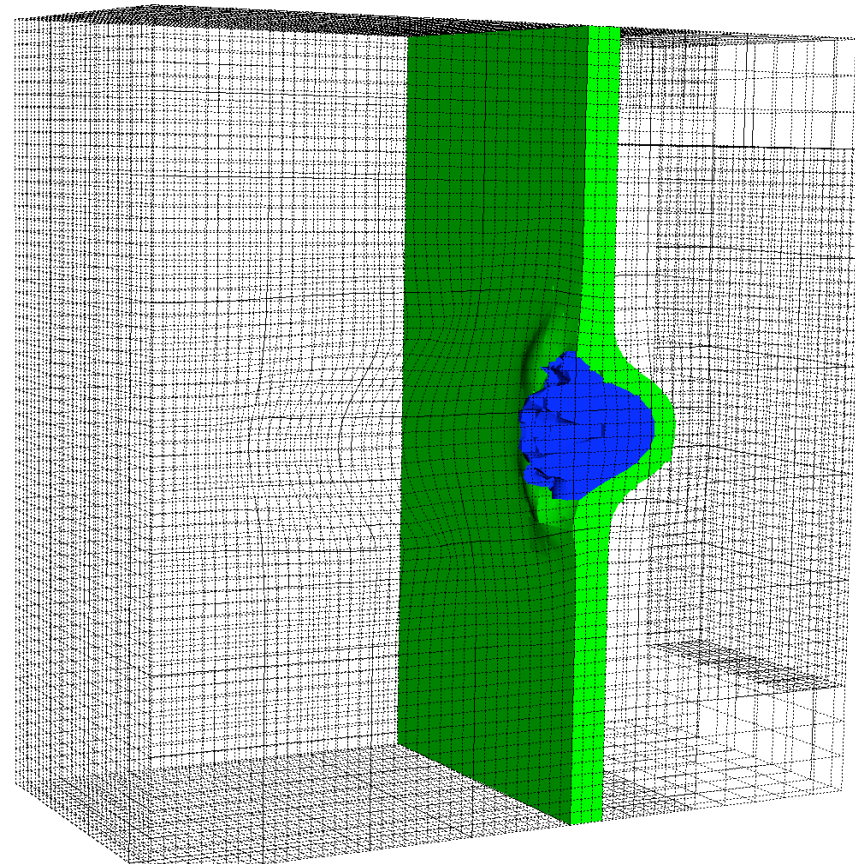
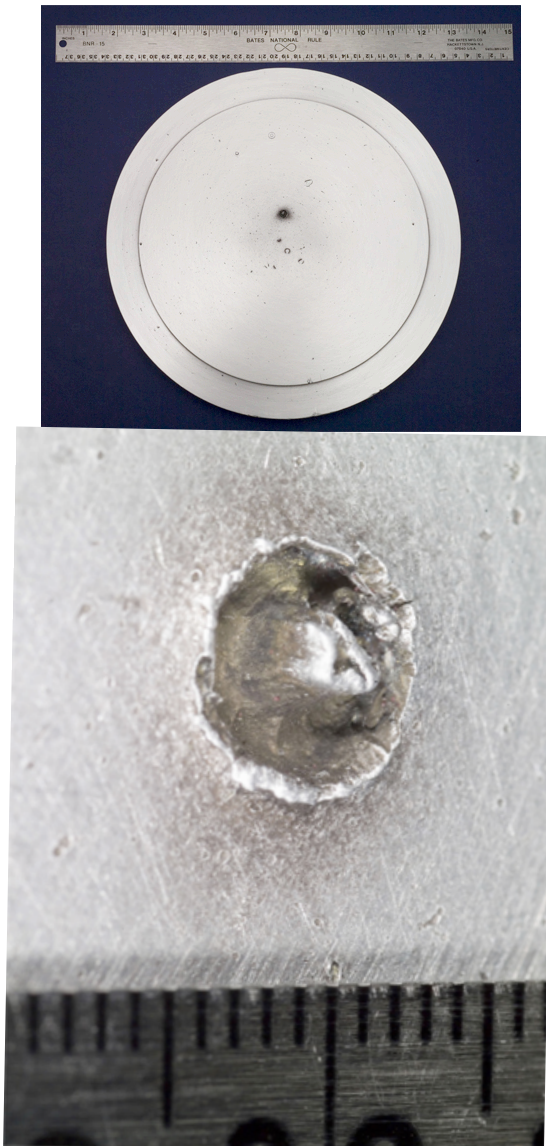
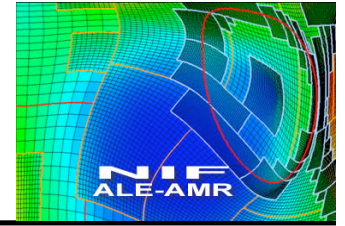


# Simulations shows spall off back plane that creates fragments for experimental validation





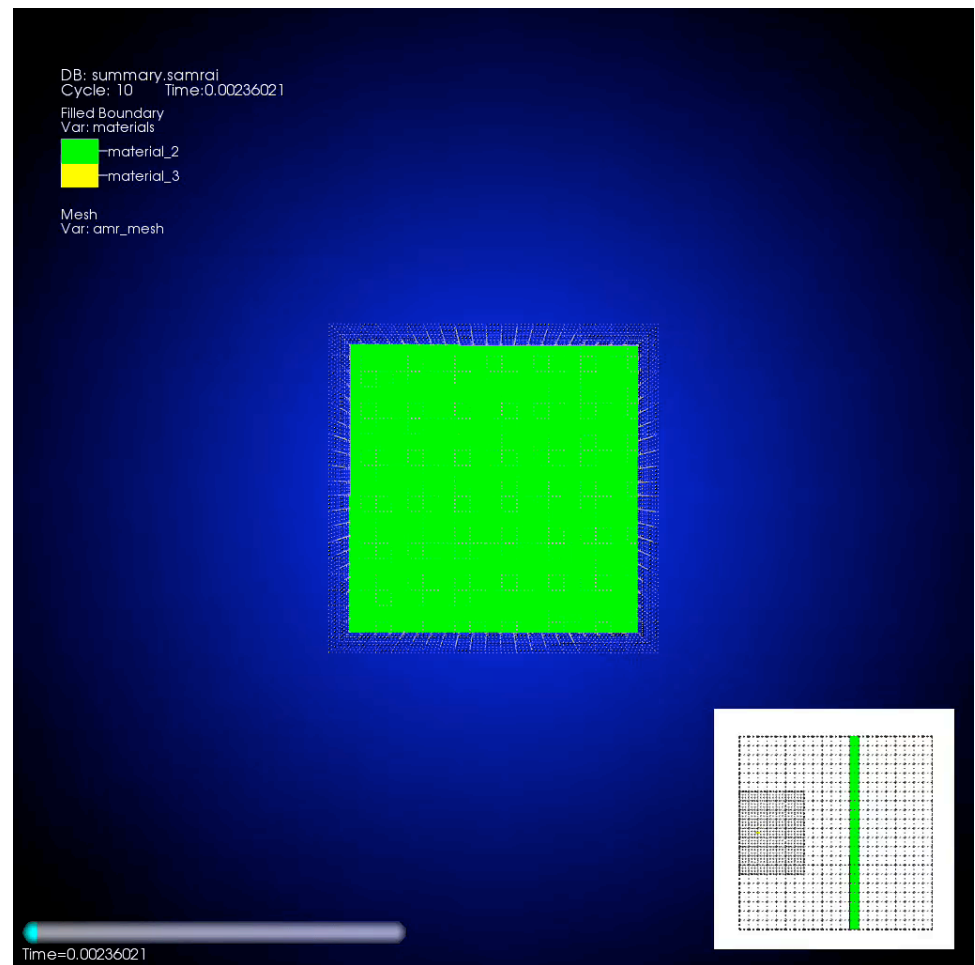
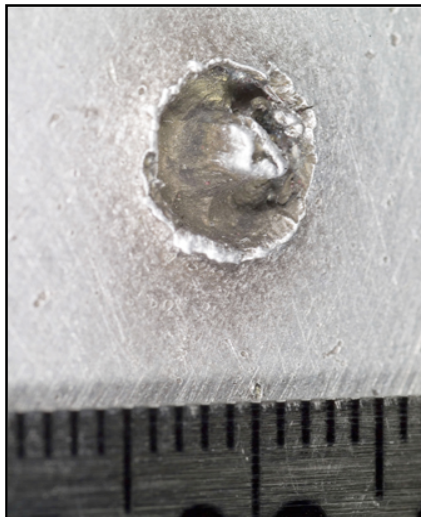
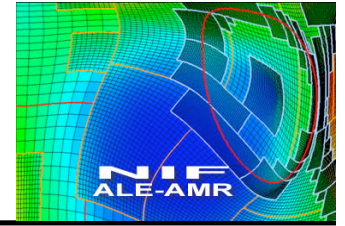
**Impact damage simulations were done to  
validate interface reconstruction and physics**



Simulation of OMEGA flapper plate damage

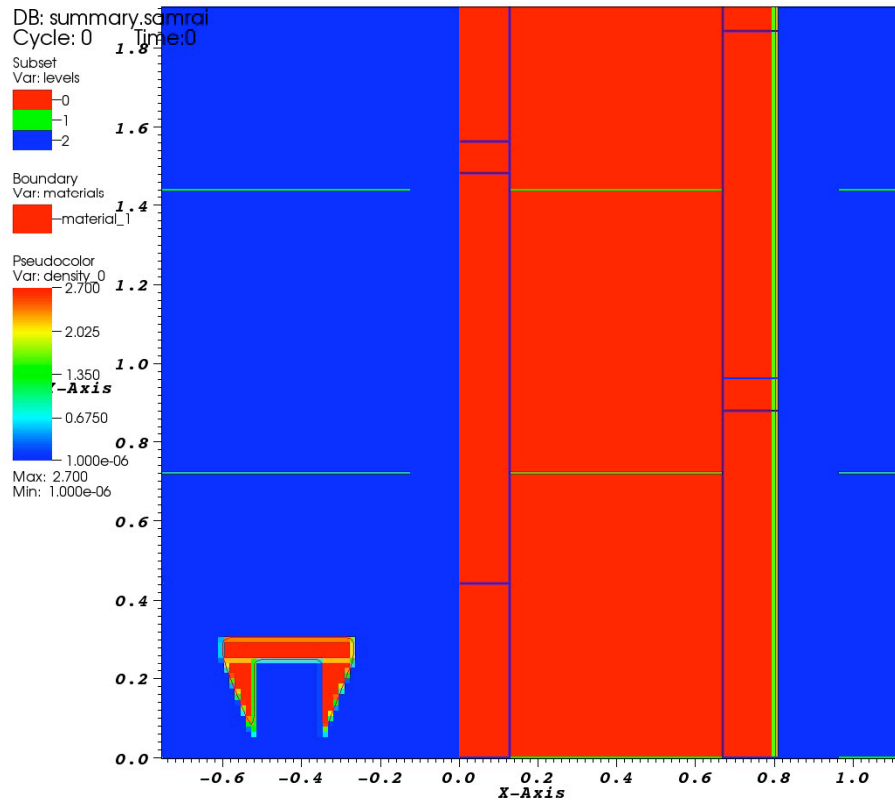


# Early Movie of projectile simulation





# Object (halfraum) launched towards a steel plate shows fragment formation -- first simulation with fragmentation model

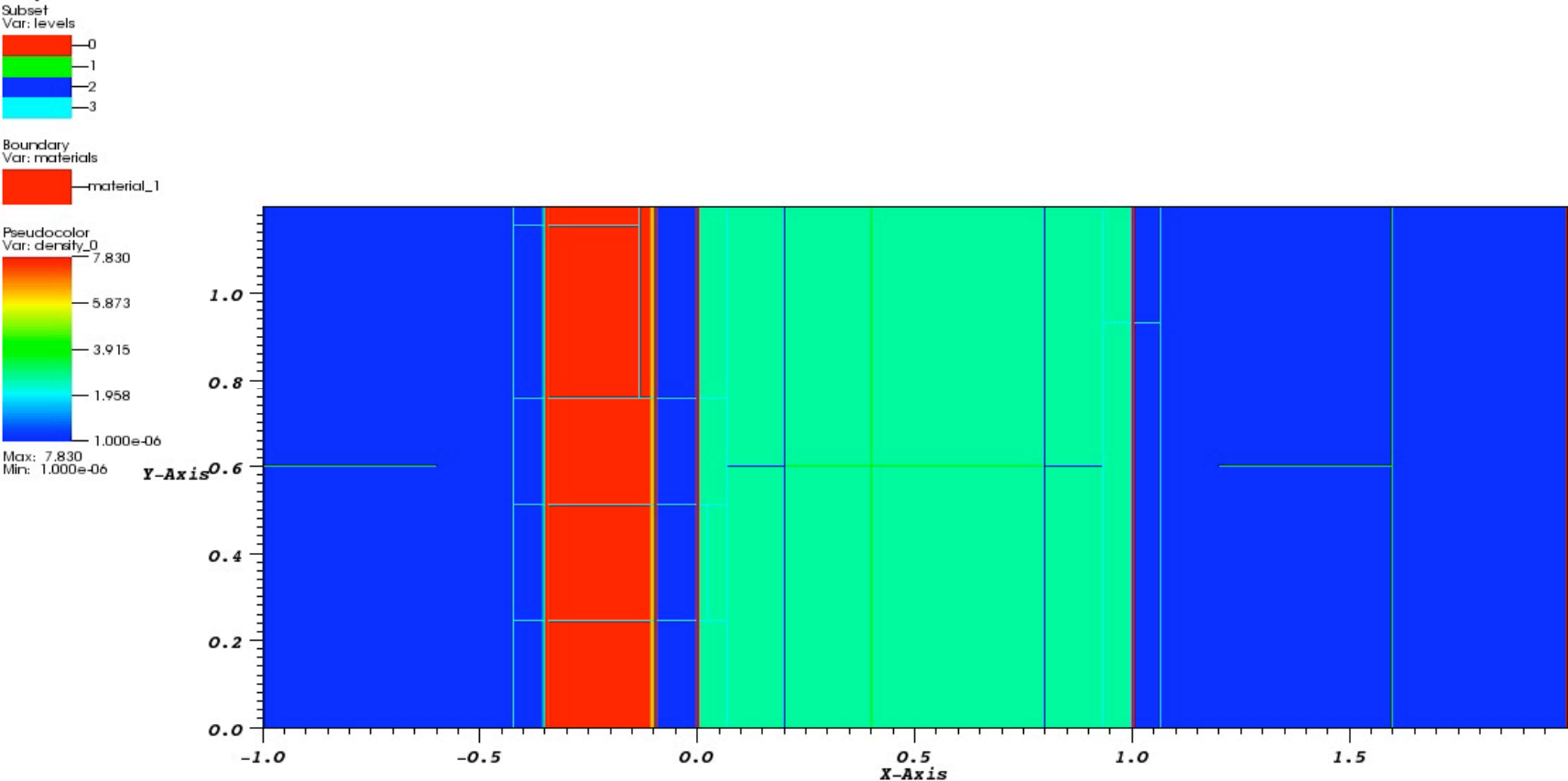


user: masters6  
Mon May 21 17:52:03 2007



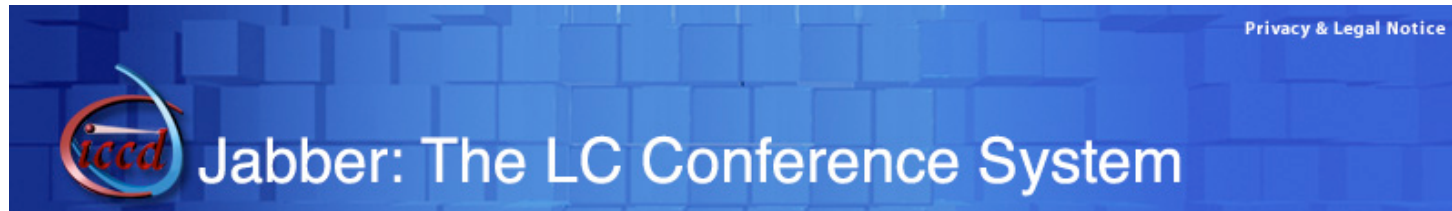
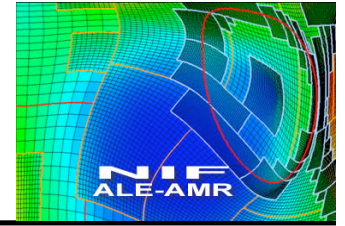
# Flyer Plate three material simulation

DB: summary.summary  
Cycle: 0      Time: 0





## **Team Development Approach: text messaging allows modern developers to work together**



- Text messaging takes over
  - Probably single most-used resource in cutting development time

Example chat dialogue was shown in talk.

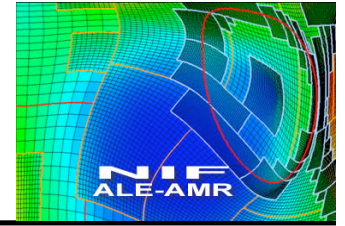
### **Chat Room Security**

- LLNL internal chat does not work from offsite unless you set up an SSH tunnel to the server.
- Not all rooms are "public"; a user must be invited before they can successfully join a room.
- There may be more rooms in existence than what you see: rooms may be defined to be invisible.



## Summary

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- **We have developed a new code for analysis of NIF chamber debris and shrapnel**
- **NIF ALE-AMR uses a combination of Arbitrary Lagrangian Eulerian algorithms and Adaptive Mesh Refinement**
- **AMR allows us to use different material models at different levels -- in progress**
- **Most issues related to implementing interface reconstruction and fragmentation models have been resolved**
- **We are continuing testing/verification/validation, while doing calculations for upcoming NIF shots**