## Particle simulation

If interactions particle-particle are included for $N$ particles $\Rightarrow \underline{N^{2}}$ forces When two particles get very near to each other - large variation of velocities in small $\Delta t \Rightarrow$ short timestep Such approach possible for $N \leq 1000$ For illustration $10^{8}$ částic, $10 \mathrm{Tflop} / \mathrm{s}$, 1 timestep - 3 hours $10^{4}$ timesteps -3 years
Larger systems

- Tree codes - interaction particle-cluster
- Particle-In-Cell - interaction particle-grid PIC is very widely applied method Aim is not accurate description of binary
 interactions, but oppositely, aim is to obtain equivalent of Vlasov equation. Thus, macroscopic electromagnetic field and motion of particles in it.
PIC - 1 timestep $\sim 0.3 \mathrm{~ms}, 10^{4}$ steps $\sim 3 \mathrm{~s}$

Spatial grid is introduced, field is calculated in nodes and interpolated among them, particles have dimensions equal to cell size - macroparticles In one dimension (1D) - slabs of thickness 1 cell v 3D cubes, particles have finite dimensions
 More velocities than dimensions possible (1D2V,1D3V,2D3V) $\Rightarrow$ currents Macroparticles may penetrate through each other (they are particle clouds) PIC - illustrative, NL problems solved and limits of analytic models found

PIC code cycle
Velocities and positions calculated from equations of motion
Charge and current densities computed via interpolation to cell nodes Fields calculated in nodes Forces via field interpolation to particle positions


Numerical solving of Vlasov equation - much slower, usually done in less dimensions (often only in 1D), noise-free, favorable for distribution tails PIC method is in fact solving of Vlasov equation via sampling
(a)

(b)


PIC solves Vlasov equation only in places, where particles are present; it is parallelized easily

Particle assignment and force interpolation
Nearest point assignment (1.order) Linear interpol. (cloud in cell 2. order)


Maxwell's equations
$N$ cells (length 1) - area length $L=N$, particle number $M$, length $\delta=1$, particle number per cell $n_{\mathrm{av}}=M / L$
Cloud-in-cell - part of charge in $x<\left(x_{i}+x_{i+1}\right) / 2$ assigned to point $i$

$$
\Delta \rho_{i}=q(1-\Delta x) \quad \Delta \rho_{i+1}=q \Delta x
$$

Electromagnetic code - Maxwell's equations - charges and currents In seminars - electrostatic code ES1 $\rightarrow$ Poisson equation

$$
\frac{\partial E}{\partial x}=\frac{\rho}{\varepsilon_{0}} \quad E(i+1)=E(i)+\frac{\rho(i)+\rho(i+1)}{2 \varepsilon_{0}}
$$

kód ES1-Fourier transform

$$
i k E_{k}=\rho_{k} / \varepsilon_{0}
$$

Force acting in $x_{i}+\Delta x$

$$
F=q E_{i}(1-\Delta x)+q E_{i+1} \Delta x
$$

Leap-frog method often used for particle motion
Equation of motion

$$
\begin{aligned}
& \mathrm{v}^{n+1 / 2}=\mathrm{v}^{n-1 / 2}+F^{n} \Delta t / m \\
& x^{n+1}=x^{n}+\mathrm{v}^{n+1 / 2} \Delta t
\end{aligned}
$$



Normalization (multiplying by constants takes time)

$$
t^{\prime}=\omega_{p e} t \quad x^{\prime}=x / \delta
$$

$\mathrm{v}^{\prime}=\frac{\mathrm{v}}{\omega_{\mathrm{p} e} \delta} \quad E^{\prime}=\frac{\varepsilon_{0} E}{e N_{a \mathrm{v}}}=\frac{\varepsilon_{0} E}{e n_{a v} \delta}$
and equations transform into form
$\frac{\mathrm{d} x^{\prime}}{\mathrm{d} t^{\prime}}=\mathrm{v}^{\prime} \quad \frac{\mathrm{d} \mathrm{v}^{\prime}}{\mathrm{d} t^{\prime}}=-E^{\prime} \quad \frac{\mathrm{d} E^{\prime}}{\mathrm{d} x^{\prime}}=1-\frac{N}{N_{a v}} \quad$ simplest case
motion of electrons solved, ions as homogenous neutralizing background Check - total energy conservation

$$
\epsilon=\sum_{j=1}^{M} \frac{m}{2} \mathrm{v}_{\mathrm{j}}^{2}+\sum_{i=1}^{N} \frac{\varepsilon_{0} E_{i}^{2}}{2} \delta=\frac{m \omega_{p e}^{2} \delta^{2}}{2}\left[\sum_{j=1}^{M} \mathrm{v}_{\mathrm{j}}^{\prime 2}+N_{a \mathrm{v}} \sum_{i=1}^{N} E_{\mathrm{i}}^{\prime 2}\right]
$$

ES1 - 1D electrostatic non-relativistic, today for education,
Moving ions, possible $B_{0} \perp x$, periodic boundaries $E(N+1)=E(1)$

