

MC modelling used in Plasma Edge Modelling

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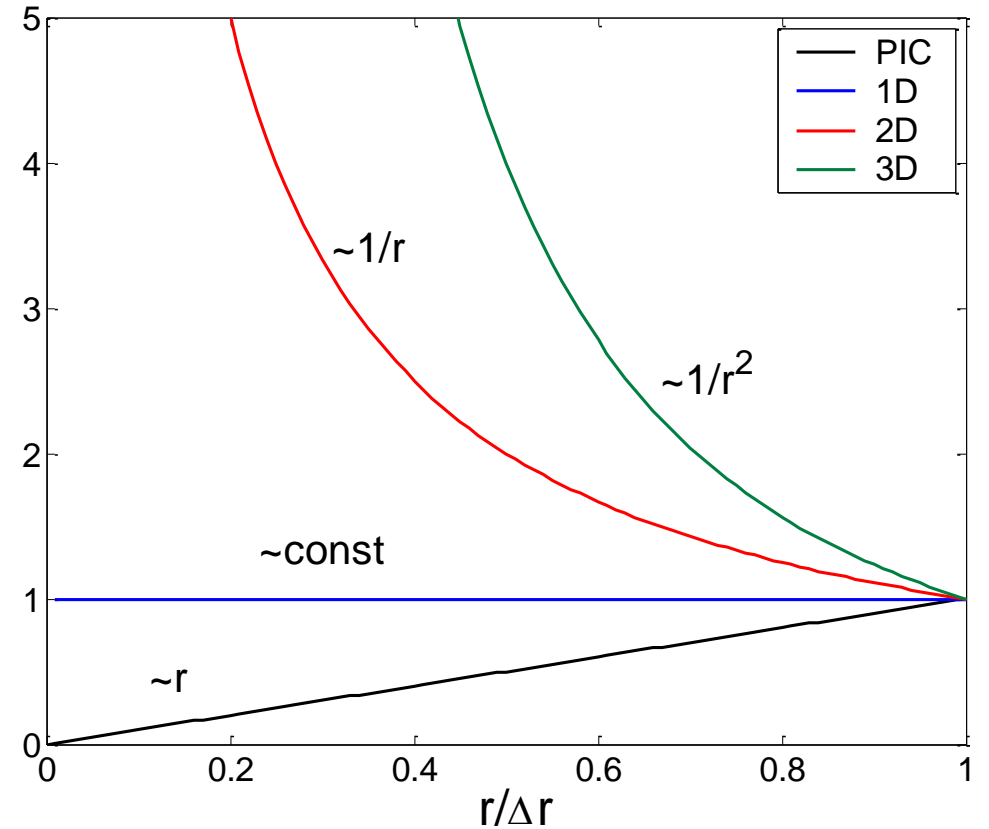
Motivation

1. Classical PIC simulates only macro fields and neglects particle collisions.
2. Inside grid cells the interaction between particles deviates from the Coulomb law

PIC
$$\left(\frac{\partial}{\partial t} + \vec{V} \frac{\partial}{\partial \vec{r}} + \frac{\vec{F}}{m} \frac{\partial}{\partial \vec{V}} \right) f(\vec{r}, \vec{V}, t) \approx 0$$

We need
$$\left(\frac{\partial}{\partial t} + \vec{V} \frac{\partial}{\partial \vec{r}} + \frac{\vec{F}}{m} \frac{\partial}{\partial \vec{V}} \right) f(\vec{r}, \vec{V}, t) = St$$

Reminder
$$V_{Coulumb} \sim \frac{n}{T^{3/2}}$$

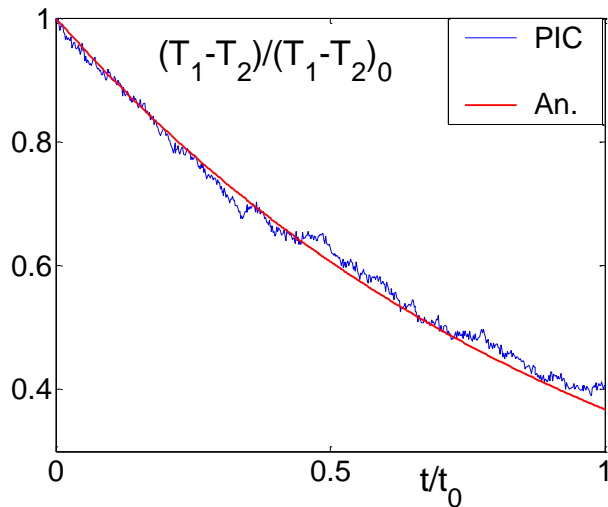


Interaction force between two particles inside the grid cell

Linear model [2]

Maxwell-distribution ↓
 Chandrasekhar coefficients ↓
 Force acting on particle ↓

$$\Delta \vec{V} = \vec{F} \Delta t + \sqrt{\Delta V_{\perp}^2 \Delta t} \vec{R}_1 \vec{e}_{\perp} + \sqrt{\Delta V_{\parallel}^2 \Delta t} R_2 \vec{e}_{\parallel}$$

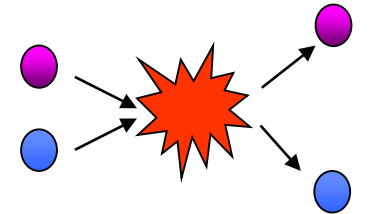


Thermal equilibration of two-temperature plasma (BIT1 code)

Nonlinear model

Calculation of Rothembluth potentials [3]
 Force acting on particle ↓
 Requires extremely **large number** of particles

Binary collision model [4]
 1. Choosing colliding pares
 2. Colliding the particles

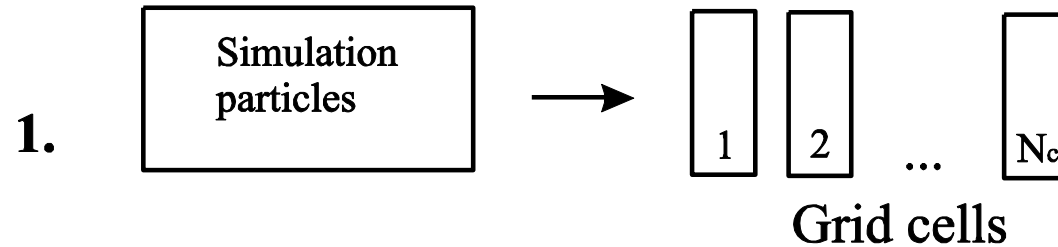


Binary collisions conserving momentum and energy

[2] A. Bergmann, *Contrib. Plasma Phys.*, 38, 1998
 [3] O.V. Batishchev, *Phys. Plasmas*, 3, 1996
 [4] T. Takizuka and H. Abe, *J. Comput. Phys.*, 25, 1977

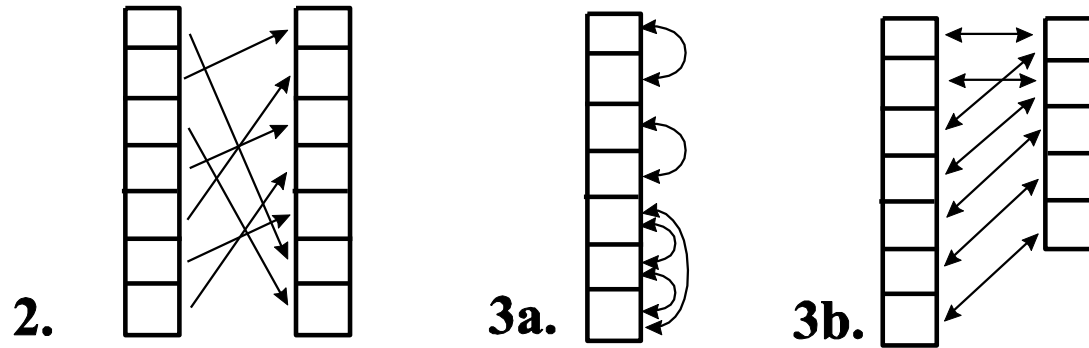
Binary collision model

Choosing of colliding pares



Particle sorting

$$\Delta r_{PIC} \sim \lambda_{Debye}$$



All particles are collided
too expensive ↓

Collision of two particles

$$\mathbf{V}' = \hat{\mathbf{O}}(\chi) \mathbf{V}$$

↑
Scattering angle

$$P(\chi) = \frac{\chi}{\langle \chi^2 \rangle_{\Delta t}} \exp\left(-\frac{\chi^2}{2\langle \chi^2 \rangle_{\Delta t}}\right),$$

$$\langle \chi^2 \rangle_{\Delta t} \sim e^4 n \Delta t / V^3$$

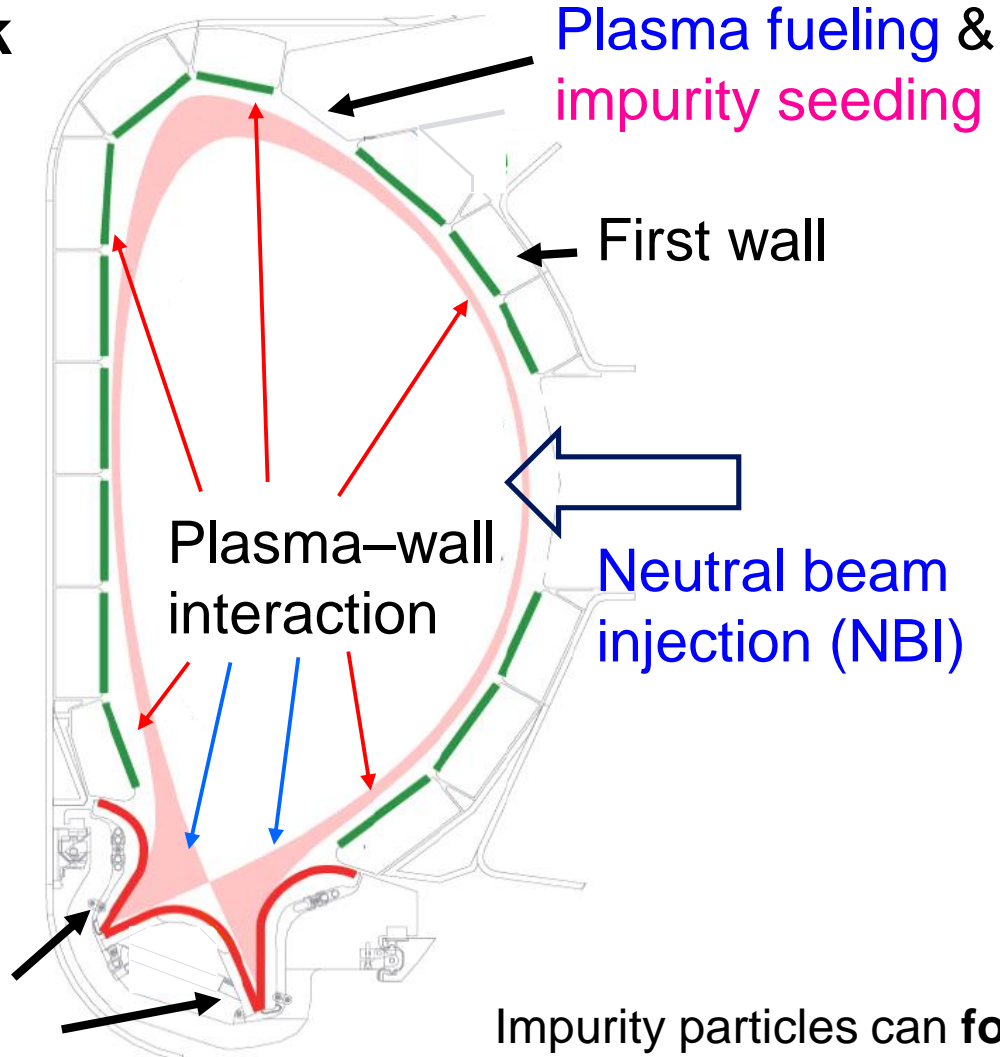
↓

Cumulative binary collision operator [5] – applicable for relatively uniform plasmas

[5] K. Nanbu, *Phys. Rev., E* 55, 1997

Questions?

Tokamak cross section



- **Atomic and molecular fuel** (D, T, D_2, T_2):
plasma fueling, NBI, plasma recycling
- Seeded **impurity particles** (N, Ne, Ar, Xe)
- Intrinsic **impurity particles**, sputtered due to plasma-wall interactions ($C, W, Be, Li, Fe, Sn, \dots$)
- Parasitic **impurity particles** penetrating into the plasma due to different processes (O, O_2, \dots)
- **Fusion product** impurity (He)
- Impurity particles used in different diagnostics (Li, \dots)

Impurity particles can form molecules: C_xH_y, N_xH_y, BeA, WA ($A=H, N, O$)

Deterministic model of particle motion

$$\frac{d}{dt} \vec{r}_i = \vec{V}_i, \quad \frac{d}{dt} \vec{V}_i = \frac{1}{m} \vec{F}_i,$$

$$\vec{F} = \vec{F}_{av.field} + \vec{F}_{collisions}$$

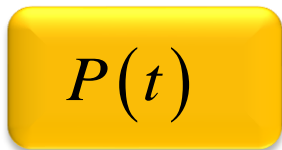


Deterministic + stochastic model of particle motion

$$\frac{d}{dt} \vec{r}_i = \vec{V}_i, \quad \frac{d}{dt} \vec{V}_i' = \frac{1}{m} \vec{F}_{av.field}^i,$$

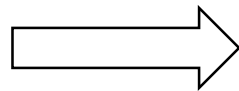
Stochastic, collision

$$\vec{V}_i' \rightarrow \vec{V}_i$$



$$P(t) = 1 - \exp(-\nu t)$$

$$\nu = nu\sigma(u)$$



Collision event



$$\begin{pmatrix} \vec{V}_1 \\ \vec{V}_2 \end{pmatrix} \Rightarrow \begin{pmatrix} \vec{V}_1' \\ \vec{V}_2' \end{pmatrix}$$

Equations conserving momentum and energy

Different ways of choosing the collision partners*

1. Counter based models
2. Non-counter based models: direct simulation MC (DSMC)

$$P(t) = 1 - \exp(-\nu t)$$

$$\nu = nu\sigma(u)$$



$$t_{col} = -\frac{\ln R}{\nu}, \quad R \in [0, 1]$$





$$\mathbf{r}, \mathbf{V}, t_{col}$$

1. Calculation of average time between collisions
2. Colliding particle after t_{col} time.

For each particle one has to **calculate** and **carry** an **additional parameter** t_{col}
Too expensive!

Null collision method [6]

1. Calculation of shortest possible collision time $t_{col}^{min} = -\frac{\ln R}{\nu_{max}}$
2. Analyzing for collision after t_{col}^{min}
3. Colliding these particles if $R' \leq \frac{P}{P_{max}} = \frac{1 - \exp(-\nu t)}{1 - \exp(-\nu_{max} t)} \approx \frac{\nu}{\nu_{max}}$

t_{col}^{min} is same for any particle of the given type – **less expensive!**

What if different collision types can take place?

[6] H.R. Skullerud, *J. Phys. D.*, 1, 1968

Collision types^[7]

$N_{\text{collided}} \rightarrow M_{\text{products}}$

- $2 \rightarrow 2$ - elastic, excitation, charge-exchange, ...
- $2 \rightarrow 1$ - recombination (radiative)
- $2 \rightarrow 3$ - dissociation, ionization
- $2 \rightarrow 4$ - double ionization, dissociative ionization
- $3 \rightarrow 2$ - recombination (three-body)

$$t_{\text{col}}^{\text{min}} = -\frac{\ln R}{\nu_{\text{max}}}, \quad \nu = \sum \nu_i$$

If $R' \leq \frac{\nu_1}{\nu_{\text{max}}}$, then collision 1 takes place

If $R' \leq \frac{\nu_1 + \nu_2}{\nu_{\text{max}}}$, then collision 2 takes place

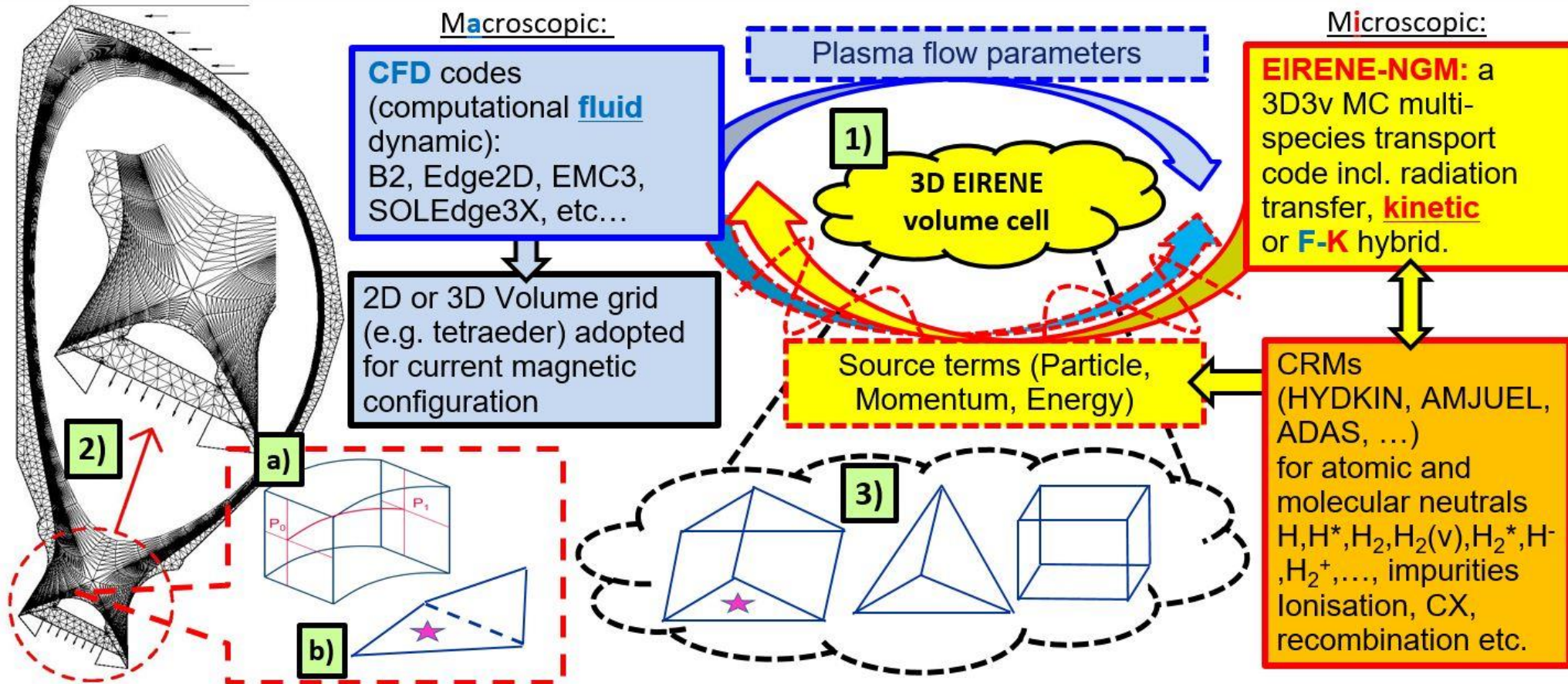
....

Frequently used in SOL simulating Linear MC codes (e.g. **EIRENE**)

Linear MC codes: target particles are not followed, but represent a background with given density, temperature and EDF

[7] D. Tskhakaya, *Contr. Plasma Phys.*, (2008); (2016)

EIRENE-NGM iterative scheme with the CFD codes [8]: NGM – Neutral Gas Module; CFD - computational fluid dynamics; CRM - collisional-radiative model

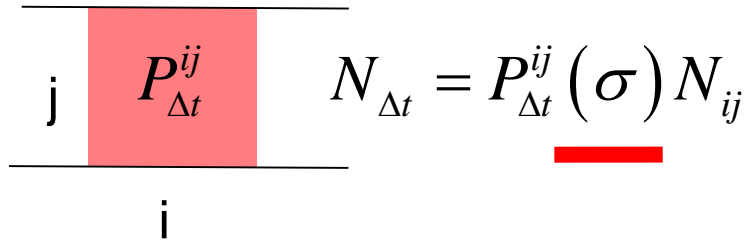


[8] <https://www.eirene.de/Basics/basics.html>

Questions?

Particles are sorted into the grid cells

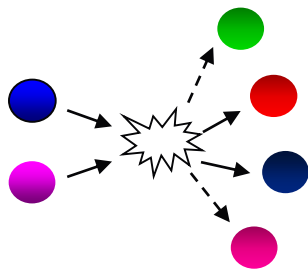
i. Decision on collision



if yes

ii. Calculation of after-collision velocities

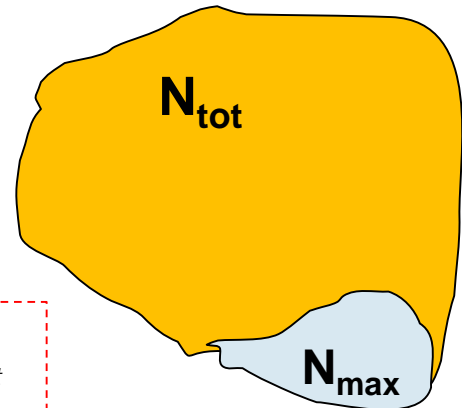
Binary collision model



particle number, energy and momentum are **conserved**

- Parameters in different cells are **statistically independent**
- Scales as $\sim N_{\text{cell}}$
- Null collisional method can be applied

1. Calculation of maximum possible number of collided particles in each cell - N_{max}
2. Analyzing only N_{max} particles.



$$N_{\text{max}} = N_{\text{tot}} P_{\text{max}}(t) \ll N_{\text{tot}}$$

[9] G. A. Bird, *Molecular Gas Dynamics and the Direct Simulation of Gas Flows*, (1994).

Charge exchange: $D + D^+ \rightarrow D^+ + D$ $\begin{pmatrix} \vec{V}_1 \\ \vec{V}_2 \end{pmatrix} \Rightarrow \begin{pmatrix} \vec{V}_2 \\ \vec{V}_1 \end{pmatrix}$ $\sigma(E)$

Elastic: $e + D \rightarrow e + D$ $\vec{U} = \vec{V}_1 - \vec{V}_2$ $\vec{U}' = \hat{\mathbf{O}}(\theta)\vec{U}$ $\vec{U}' F \begin{pmatrix} \vec{V}_1 \\ \vec{V}_2 \end{pmatrix} \Rightarrow \begin{pmatrix} \vec{V}_1' \\ \vec{V}_2' \end{pmatrix}$ $\sigma(E, \theta)$

Excitation: $e + D \rightarrow e + D^{(n)}$ $\vec{U} = \vec{V}_1 - \vec{V}_2$ $\vec{U}' = \hat{\mathbf{O}}(\theta)\vec{U}$ $\vec{V}_1 \rightarrow \vec{V}_1' = \vec{V}_1 = \sqrt{1 - \frac{E_{th}}{E_0}}$

Ionization: $e + D \rightarrow 2e + D^+$ $\sigma(E, \theta, E_1, \theta_1)$ $\vec{U}' F \begin{pmatrix} \vec{V}_1' \\ \vec{V}_2' \end{pmatrix} \Rightarrow \begin{pmatrix} \vec{V}_1'' \\ \vec{V}_2' \end{pmatrix}$ $\sigma(E, \theta, n)$

Double ionization: $e + Ne \rightarrow 3e + Ne_n^{++}$ $\sigma(E, \theta, E_1, \theta_1, E_2, \theta_2, n)$